Curved SL(5) exceptional field theory

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Based on Bosque, Hassler, Lüst, EM arXiv:1602.xxxx

- "Fluctuations" (scalar degrees of freedom)
- Introduce generalised vielbeine $\tilde{\mathbb{E}}_{a}^{\bar{a}}$, \bar{a} is SO(5) index
- Generalised metric $\mathcal{M}_{ab} = \tilde{\mathbb{E}}_a{}^{\bar{a}}\tilde{\mathbb{E}}_b{}^{\bar{b}}\delta_{\bar{a}\bar{b}}$ (SO(5) structure)
- \bullet Define connection for ${\cal L}$

$$\tilde{\nabla}_{ab}V^{c} = \nabla_{ab}V^{c} + \tilde{\Gamma}_{ab,d}{}^{c}V^{d} - w\gamma_{ab}V^{c}, \qquad (1)$$

$$\tilde{\Gamma}_{ab,c}{}^{d} = -\tilde{\mathbb{E}}^{\bar{c}}{}_{c}\nabla_{ab}\tilde{\mathbb{E}}_{\bar{c}}{}^{d}, \qquad \gamma_{ab} = \frac{5}{7}D_{ab}\ln e, \qquad (2)$$

e_μ^{μ̄} is external vielbein
Γ̃ is not SO(5) invariant (we will restore this in the potential)

Generalised torsion

• Generalised Torsion:

$$\left(\mathcal{L}^{\tilde{\nabla}}_{\Lambda} - \mathcal{L}_{\Lambda}\right) V^{a} = \frac{1}{2} T_{bc,d}{}^{a} \Lambda^{bc} V^{d} - \frac{1}{2} w T_{bc} \Lambda^{bc} V^{a}, \qquad (3)$$

• Covariant under *L*!

Irreps:

$$T_{ab,c}{}^{d} = \frac{1}{2} \delta^{d}_{[a} \tilde{S}_{b]c} + \frac{1}{2} \epsilon_{abcef} \tilde{Z}^{ef,d} - \frac{1}{27} \left(25 \, \delta^{d}_{[a} T_{b]c} + 5 \, \delta^{d}_{c} T_{ab} \right) \,.$$
(4)

• Explicitly,

$$\begin{split} \tilde{S}_{ab} &= T_{c(a,b)}{}^{c} = 4\tilde{\Gamma}_{c(a,b)}{}^{c} ,\\ \tilde{Z}^{ab,c} &= \frac{1}{3!} \epsilon^{abdef} T_{de,f}{}^{c} = \frac{1}{2} \epsilon^{abdef} \tilde{\Gamma}_{de,f}{}^{c} - \frac{1}{2} \epsilon^{abcde} \tilde{\Gamma}_{[fd,e]}{}^{f} , \quad (5)\\ T_{ab} &= -\frac{5}{3} T_{c[a,b]}{}^{c} = \frac{6}{5} \gamma_{ab} + \tilde{\Gamma}_{e[a,b]}{}^{e} , \end{split}$$

• The torsion is not invariant under SO(5)!

• Construct independent generalised diffeomorphism scalar densities

$$A = \tilde{S}_{ab}\tilde{S}_{cd}\mathcal{M}^{ac}\mathcal{M}^{bd}, \qquad B = \left(\tilde{S}_{ab}\mathcal{M}^{ab}\right)^{2},$$

$$C = \mathcal{M}^{ac}\mathcal{M}^{bd}T_{ab}T_{cd}, \qquad D = \mathcal{M}_{ab}\mathcal{M}_{cd}\mathcal{M}_{ef}\tilde{Z}^{ac,e}\tilde{Z}^{bd,f},$$

$$E = \mathcal{M}_{ab}\mathcal{M}_{cd}\mathcal{M}_{ef}\tilde{Z}^{ac,b}\tilde{Z}^{de,f}, \qquad F = \mathcal{M}^{ac}\mathcal{M}^{bd}\tilde{\nabla}_{ab}T_{cd}.$$
(6)

 \bullet Combine them to form ${\rm SO}(5)$ invariant (up to constraints):

$$V_{1} = -\frac{1}{16}\mathcal{M}^{ac}\mathcal{M}^{bd}\tilde{S}_{ab}\tilde{S}_{cd} + \frac{1}{32}\mathcal{M}^{ac}\mathcal{M}^{bd}\tilde{S}_{ac}\tilde{S}_{bd} - \frac{5}{12}\mathcal{M}^{ac}\mathcal{M}^{bd}T_{ab}T_{cd} - \frac{1}{2}\mathcal{M}_{ab}\mathcal{M}_{cd}\mathcal{M}_{ef}\tilde{Z}^{ac,e}\tilde{Z}^{bd,f} + \frac{1}{2}\mathcal{M}_{ab}\mathcal{M}_{cd}\mathcal{M}_{ef}\tilde{Z}^{ac,b}\tilde{Z}^{ed,f} - \mathcal{M}^{ac}\mathcal{M}^{bd}\tilde{\nabla}_{ab}T_{cd}$$
(7)

• Up to constraints we can write this as

$$V_{1} = -\frac{1}{2} \nabla_{ab} \mathcal{M}^{ac} \nabla_{cd} \mathcal{M}^{bd} + \frac{1}{8} \mathcal{M}^{ac} \mathcal{M}^{bd} \nabla_{ab} \mathcal{M}^{ef} \nabla_{cd} \mathcal{M}_{ef} + \frac{1}{2} \mathcal{M}^{ac} \mathcal{M}^{bd} \nabla_{ab} \mathcal{M}^{ef} \nabla_{ec} \mathcal{M}_{df} - \mathcal{M}^{ac} \nabla_{ab} \nabla_{cd} \mathcal{M}^{bd} + \mathcal{M}^{ac} \mathcal{M}^{bd} \left(\frac{1}{2} \omega_{ae,c}{}^{e} \omega_{bf,d}{}^{f} - \frac{1}{2} \omega_{ae,c}{}^{f} \omega_{bf,d}{}^{e} + \frac{1}{2} \omega_{ae,b}{}^{e} \omega_{df,c}{}^{f} - \frac{1}{2} \omega_{ae,b}{}^{f} \omega_{df,c}{}^{e} - \omega_{ae,d}{}^{f} \omega_{fc,b}{}^{e} - \omega_{ae,f}{}^{e} \omega_{cd,b}{}^{f} \right).$$

$$\tag{8}$$

- ω^2 terms are background fluxes and appear also in DFT_{WZW} .
- Section condition term is

$$\Delta_{0} = \frac{1}{2} \mathcal{M}^{ac} \mathcal{M}^{bd} \left(-\mathring{\Gamma}_{ae,b}{}^{e}\mathring{\Gamma}_{df,c}{}^{f} - 2\mathring{\Gamma}_{ab,c}{}^{e}\mathring{\Gamma}_{ef,d}{}^{f} + \mathring{\Gamma}_{ae,c}{}^{e}\mathring{\Gamma}_{bf,d}{}^{f} + \mathring{\Gamma}_{af,b}{}^{e}\mathring{\Gamma}_{de,c}{}^{f} - \mathring{\Gamma}_{af,c}{}^{e}\mathring{\Gamma}_{be,d}{}^{f} \right)$$
(9)

where

$$\tilde{\bar{}}_{ab,c}{}^d = -\tilde{\mathbb{E}}_c{}^{\bar{c}}D_{ab}\tilde{\mathbb{E}}_{\bar{c}}{}^d.$$
(10)

- Can construct the full "curved" SL(5) EFT action this way.
- Everything is manifestly coordinate-invariant.
- Similar to gauged EFT but "twists" $E_{ab} \in GL(10)$.
- When M_{10} locally flat \Rightarrow SL(5) EFT.
- Then coordinate patches are patched with SL(5)!
- Do we need local flatness? Background-independence? (Hohm, Marques) Applying the section condition? SUSY?...

- Conditions for local flatness. Better connections?
- What 4-manifolds (3-manifolds) can be embedded into locally flat *M*₁₀?
- Section condition?
- Global sections as reduced structure group? Non-geometric spaces?
- Scherk-Schwarz (probably need local flatness!)
- Non-abelian T-duality?

Module(<i>w</i>)	Representations	Gauge field	Field strength
$\mathcal{A}(1/5)$	10	\mathcal{A}^{ab}	\mathcal{F}^{ab}
$\mathcal{B}(2/5)$	5	\mathcal{B}_{a}	\mathcal{H}_{a}
$\mathcal{C}(3/5)$	5	\mathcal{C}^{a}	\mathcal{J}^{a}
$\mathcal{D}(4/5)$	10	${\cal D}_{\sf ab}$	\mathcal{K}_{ab}

•-product (wedge product)

We define a • product between these spaces.

$$\begin{array}{c|cccc} \bullet & \mathcal{A}(1/5) & \mathcal{B}(2/5) & \mathcal{C}(3/5) & \mathcal{D}(4/5) \\ \hline \mathcal{A}(1/5) & \mathcal{B}(2/5) & \mathcal{C}(3/5) & \mathcal{D}(4/5) & \mathcal{S}(1) \\ \hline \mathcal{B}(2/5) & \mathcal{C}(3/5) & \mathcal{D}(4/5) & \mathcal{S}(1) \\ \hline \mathcal{C}(3/5) & \mathcal{D}(4/5) & \mathcal{S}(1) \\ \hline \mathcal{D}(4/5) & \mathcal{S}(1) \\ \hline & & (\mathcal{A}_{1} \bullet \mathcal{A}_{2})_{a} = \frac{1}{4} \epsilon_{abcde} \mathcal{A}_{1}^{bc} \mathcal{A}_{2}^{de} , \\ & & (\mathcal{A} \bullet \mathcal{B})^{a} = \mathcal{A}^{ab} \mathcal{B}_{b} , \\ & & (\mathcal{A} \bullet \mathcal{C})_{ab} = \frac{1}{4} \epsilon_{abcde} \mathcal{A}^{cd} \mathcal{C}^{e} , \\ & & \mathcal{A} \bullet \mathcal{D} = \frac{1}{2} \mathcal{A}^{ab} \mathcal{D}_{ab} , \\ & & (\mathcal{B}_{1} \bullet \mathcal{B}_{2})_{ab} = \mathcal{B}_{2[a} \mathcal{B}_{1]b} , \\ & & & \mathcal{B} \bullet \mathcal{C} = \mathcal{B}_{a} \mathcal{C}^{a} , \end{array}$$

(11)

Want nilpotent derivative

$$\mathcal{A}(1/5) \xleftarrow{\hat{\partial}} \mathcal{B}(2/5) \xleftarrow{\hat{\partial}} \mathcal{C}(3/5) \xleftarrow{\hat{\partial}} \mathcal{D}(4/5).$$
 (12)

Use

$$\hat{\partial}\mathcal{B}^{ab} = \frac{1}{2}\epsilon^{abcde}\nabla_{cd}\mathcal{B}_{e}, \qquad \hat{\partial}\mathcal{C}_{a} = \nabla_{ba}\mathcal{C}^{b}, \qquad \hat{\partial}\mathcal{D}^{a} = \frac{1}{2}\epsilon^{abcde}\nabla_{bc}\mathcal{D}_{de},$$
(13)

Constraints \Rightarrow Nilpotency, covariant under \mathcal{L} .

• and $\hat{\partial}$ satisfy for all $\Lambda \in \mathcal{A}(1/5)$ and $\mathcal{T} \in \mathcal{B}(2/5)$ or $\mathcal{C}(3/5)$,

$$\mathcal{L}_{\Lambda}\mathcal{T} = \Lambda \bullet \left(\hat{\partial}\mathcal{T}\right) + \hat{\partial}\left(\Lambda \bullet \mathcal{T}\right) \,. \tag{14}$$