

TITLE : QUANTUM ALGORITHMS

"Solving mathematical problems with quantum systems"

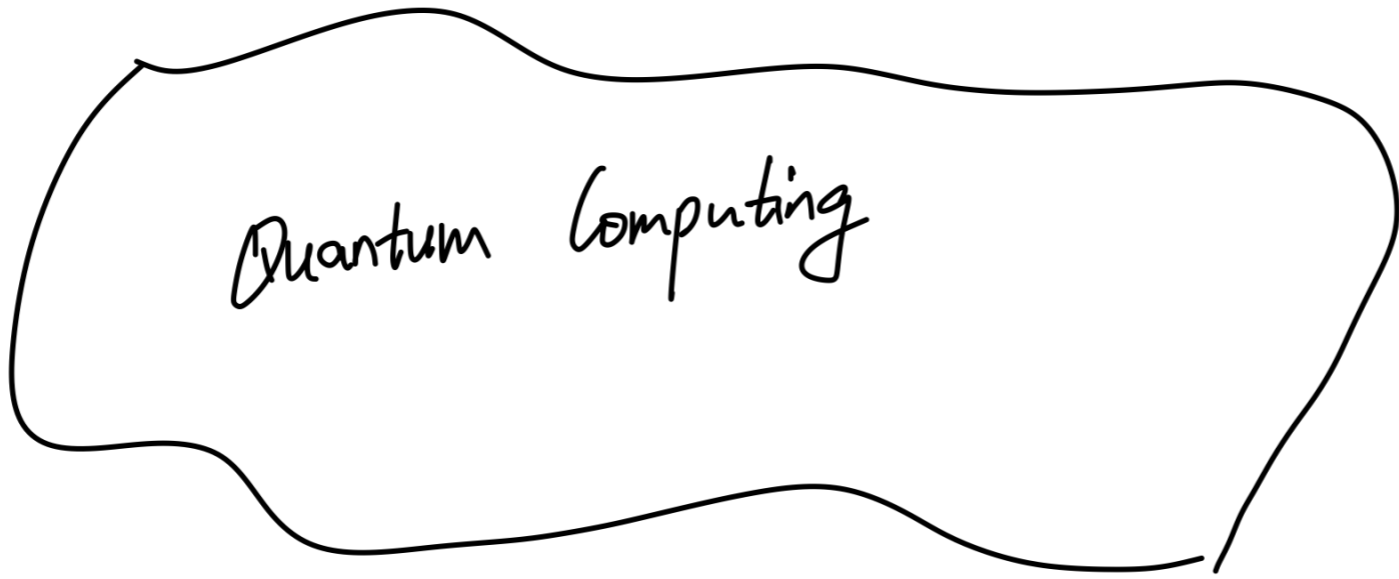
Joonwoo Bae (QIT @ KAIST, EE, KAIST)

"What is quantum computation?"

Lecture (the 8th School of Mesoscopic Physics)

- Basics of quantum information processing
- Computing with quantum systems
- Examples of quantum algorithms

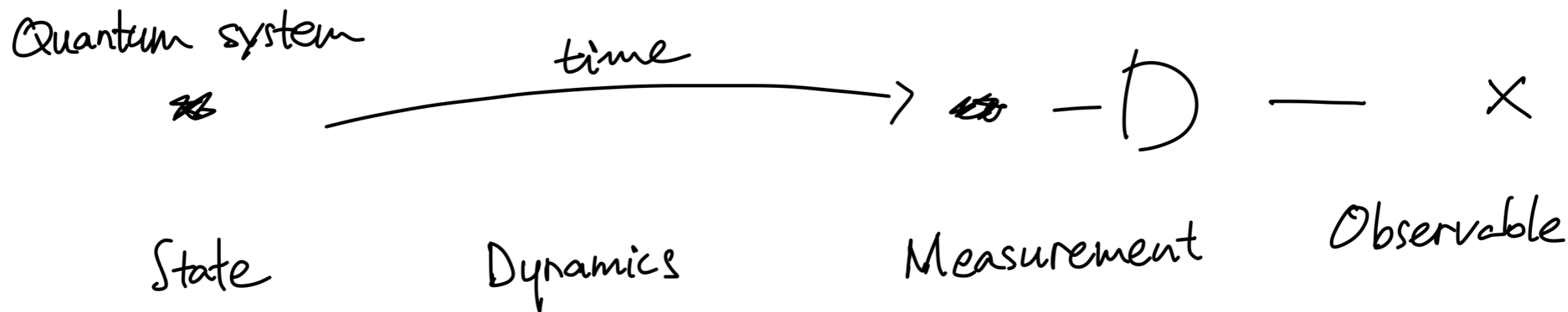
\otimes^n
107



x_1 solution
 x_2
 x_3
 \vdots
 x_n

I. Basics of Quantum Information Processing

Quantum theory is a mathematical model of the microscopic world.



Textbook.	$\psi(x,t)$	$i \partial_t \psi = H \psi$ ($t_0 = 1$)	$ \psi(x,t) ^2 \sim p(x,t)$	$A = A^\dagger$
Description of a quantum system		Eq. of motion for $\psi(x,t)$	Probabilistic nature of measurement outcomes	Characterization of the parameters that can be observed

Quantum State

Dynamics

Measurement

Observable

Textbook.

$$\psi(x,t)$$

$$i \partial_t \psi = H \psi$$

$$(t_0 = 1)$$

$$|\psi(x,t)|^2 \sim p(x,t)$$

$$A = A^\dagger$$

Description
of a quantum system

Eq. of motion
for $\psi(x,t)$

Probabilistic
nature of
measurement
outcomes

Characterization
of the
parameters that
can be observed

Recall.

$$\psi = \sum_n c_n \phi_n \rightsquigarrow \{ \phi_n \} \text{ basis}$$

$$\psi \in \text{span} \{ \phi_n \} = \mathcal{V} \text{ (vector space)}$$

inner product

$$\langle \psi, \varphi \rangle = \int d\mu(x) \psi^*(x) \varphi(x) \rightsquigarrow |\psi|^2$$

quantum measurement

Mathematical structure

- Quantum states introduce a vector space
- A quantum measurement introduces an inner product.

A vector space with an inner product \sim Hilbert space, \mathcal{H}
Dirac notation

$\vec{x} \in \mathcal{H}$	element in \mathcal{H}		$ x\rangle \in \mathcal{H}$
$(\vec{y})^\dagger = (\vec{y}^*)^T$	Hermitian conjugate		$\langle y = (y\rangle)^\dagger$
$\langle \vec{x}, \vec{y} \rangle = \vec{x}^\dagger \cdot \vec{y}$	inner product		$\langle x, y \rangle = \langle x y\rangle$
$\vec{y} = A \vec{x}$			$ y\rangle = A x\rangle$
$A = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \ddots & \vdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$	Matrix		$A = \sum_{ij} a_{ij} i\rangle\langle j $

Reconstructing Quantum Theory

✓ State ✓ Dynamics ✓ Measurement ✓ Observable

$$\psi(x,t)$$

$$i \partial_t \psi = H \psi$$

($t_0 = 1$)

$$|\psi(x,t)|^2 \sim p(x,t)$$

$$A = A^\dagger$$

Description
of a quantum system

Eq. of motion
for $\psi(x,t)$

Probabilistic
nature of
measurement
outcomes

Characterization
of the
parameters that
can be observed

$$|\psi(x,t)\rangle \in \mathcal{H}$$

$$|\psi(t)\rangle = U(t) |\psi(t_0)\rangle$$

U : unitary transformation

$$U U^\dagger = U^\dagger U = I$$

$$|\langle \psi | i \rangle|^2$$

(inner product)

Quantum measurement

a measurement in basis $\{|i\rangle\}_{i=1}^n = \{|1\rangle, |2\rangle, \dots, |n\rangle\}$

$$p(i | \psi) = |\langle i | \psi \rangle|^2 = \langle i | \psi \rangle \langle i | \psi \rangle^*$$
$$= \langle \psi | i \rangle \langle i | \psi \rangle$$

$$1 = \sum_{i=1}^n p(i | \psi) = \langle \psi | \left(\sum_{i=1}^n |i\rangle\langle i| \right) | \psi \rangle = \langle \psi | I | \psi \rangle$$

note. trace

Def. $\text{tr} A = \sum_i \langle i | A | i \rangle = \sum_i \lambda_i$, $\{\lambda_i\} = \text{eig}(A)$

• $\text{tr} AB = \text{tr} BA$, $AB \neq BA$

• $\text{tr} ABC = \text{tr} CAB$

a measurement in a basis

$$p(\lambda_i|\psi) = \langle \psi | \lambda_i | \psi \rangle = \text{tr} [(|\psi\rangle\langle\psi|) |\lambda_i\rangle\langle\lambda_i|]$$

a general description of a quantum measurement

$$\{ M_i \}_{i=1}^n \text{ such that } p(\lambda_i|\psi) = \text{tr} [|\psi\rangle\langle\psi| M_i]$$

$$i) p(\lambda_i|\psi) = \text{tr} [|\psi\rangle\langle\psi| M_i] \geq 0 \iff M_i \geq 0$$

$$\text{note. } A \geq 0 \iff \forall |\psi\rangle, \text{tr} [A |\psi\rangle\langle\psi|] \geq 0 \iff \text{eig } A \geq 0$$

$$ii) 1 = \sum_i p(i|4) = \text{tr} [14 \times 4 | \sum_i M_i] \Leftrightarrow \sum_i M_i = I$$

A generalized measurement is described by positive-operator-valued-measure (POVM) elements $\{M_i\}$ satisfying $M_i \geq 0 \forall i$, $\sum_i M_i = I$.

Reconstructing Quantum Theory

State

Dynamics

Measurement

POVM $\{M_i\}$

$|\psi\rangle$

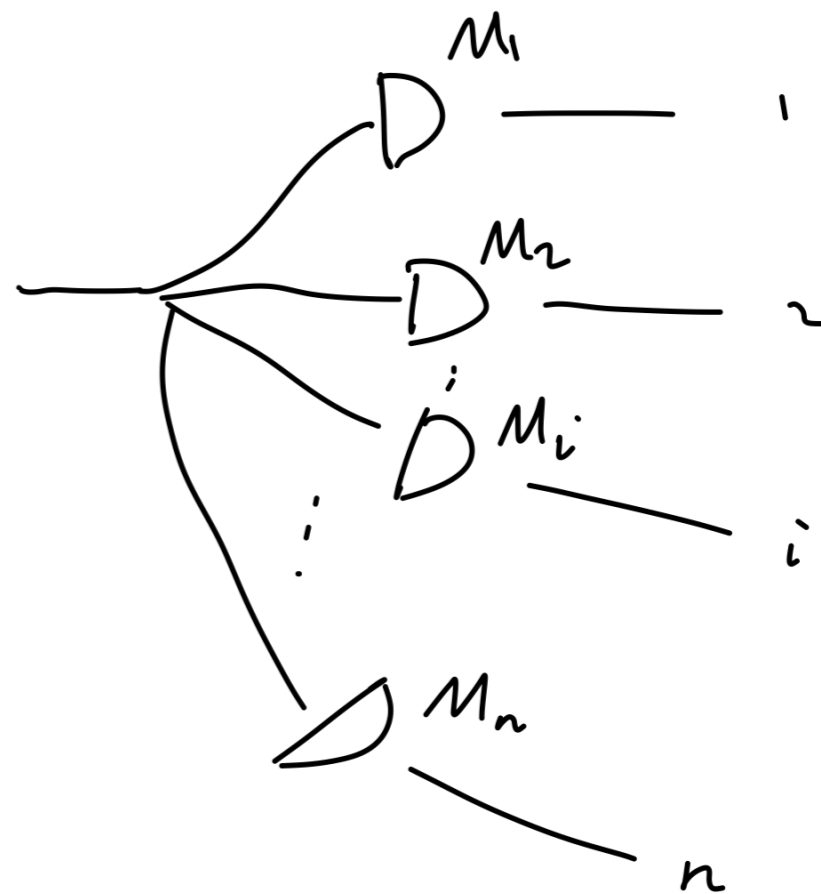
~ Physical interpretation?

probabilities

$$\text{tr} [|\psi\rangle\langle\psi| M_i]$$

$$|\psi\rangle \longrightarrow |\psi\rangle\langle\psi|$$

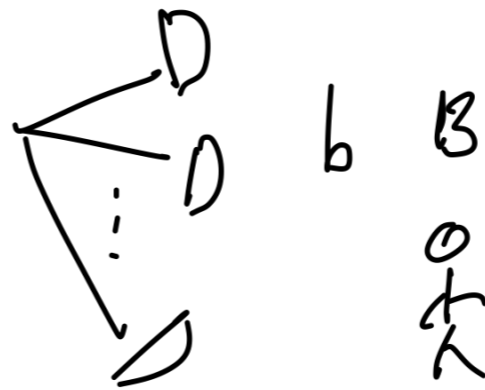
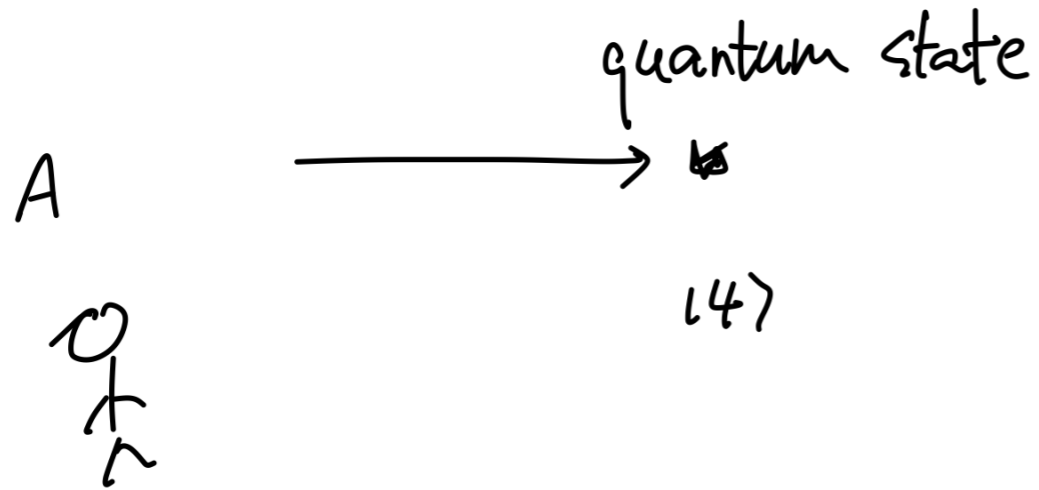
$$p(i|\psi) = \text{tr} [|\psi\rangle\langle\psi| M_i]$$



POVM

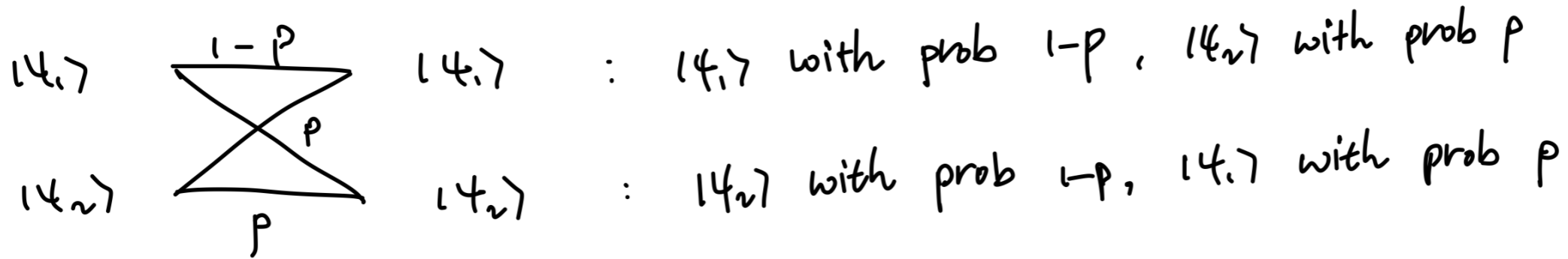
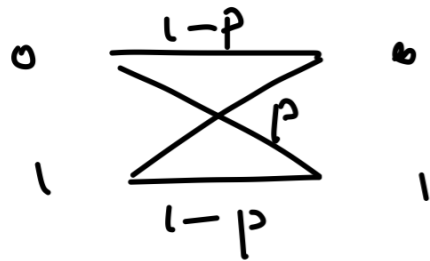
~ description of detectors
in a quantum measurement

a preparation game

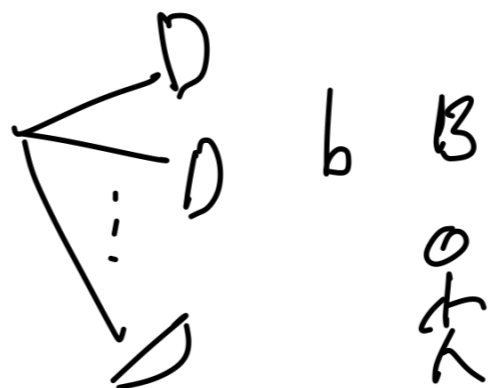
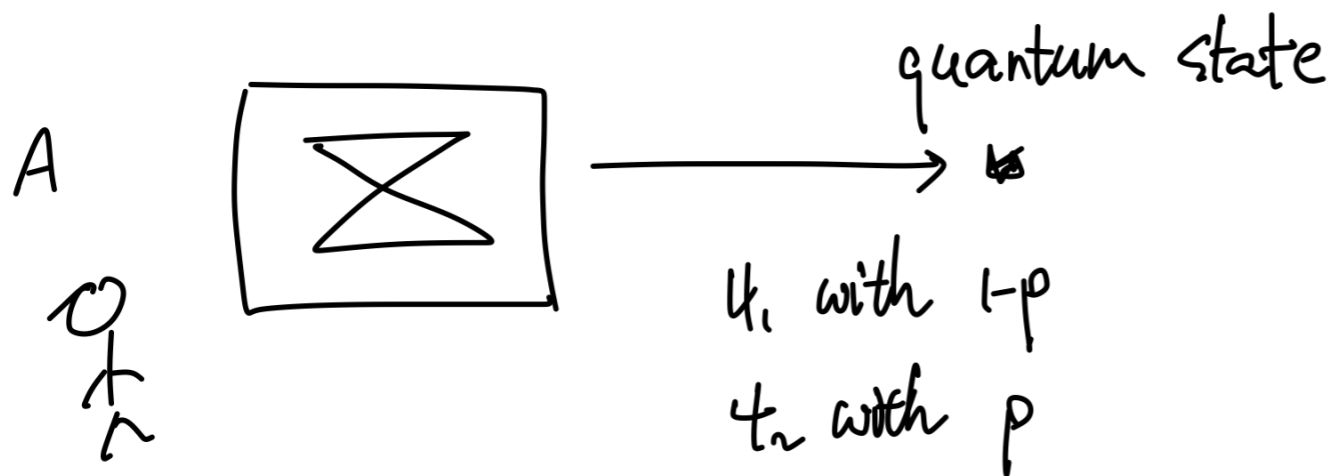


$$\text{prob}(b|4) = \text{tr}[M_b |4\rangle\langle 4|]$$

Binary Symmetric Channel



a preparation game



~~$$\text{prob}(b|\psi) = \text{tr}[M_b |\psi\rangle\langle\psi|]$$~~

Note. $(1-p)|\psi_1\rangle\langle\psi_1| + p|\psi_2\rangle\langle\psi_2|$

state ψ_1 with prob $1-p$

ψ_2 with prob p

\Leftarrow

$\text{Prob}[b | \psi_1 \text{ with } 1-p, \psi_2 \text{ with } p]$

$$= (1-p) \text{Prob}[b | \psi_1] + p \text{Prob}[b | \psi_2]$$

$$= (1-p) \text{tr}[M_b |\psi_1\rangle\langle\psi_1|] + p \text{tr}[M_b |\psi_2\rangle\langle\psi_2|]$$

$$= \text{tr}[M_b ((1-p)|\psi_1\rangle\langle\psi_1| + p|\psi_2\rangle\langle\psi_2|)]$$

$\underbrace{\hspace{2cm}}$
 POVM

$\underbrace{\hspace{10cm}}$
 state

A general description of a quantum state

$$\rho = p_1 |\psi_1\rangle\langle\psi_1| + p_2 |\psi_2\rangle\langle\psi_2| + \dots = \sum_i p_i |\psi_i\rangle\langle\psi_i|$$

i) $\rho \geq 0$ ii) $\text{tr} \rho = 1$

$$\sum_i M_i = I. \quad \text{tr}[\rho \sum_i M_i] = 1 \quad \forall \text{ POVM}$$

operational equivalence of quantum states

$$\rho = \sigma \quad \text{iff} \quad \forall M, \quad \text{tr}[\rho M] = \text{tr}[\sigma M]$$

\Leftrightarrow ρ and σ cannot be distinguished, thus identical!

$$\rho \neq \sigma \quad (\Leftrightarrow) \quad \exists M \text{ such that } \text{tr}[\rho M] \neq \text{tr}[\sigma M]$$

Quantum Dynamics

$$\rho \longrightarrow U \rho U^\dagger, \quad U : \text{unitary transformation}$$

$$U U^\dagger = U^\dagger U = I$$

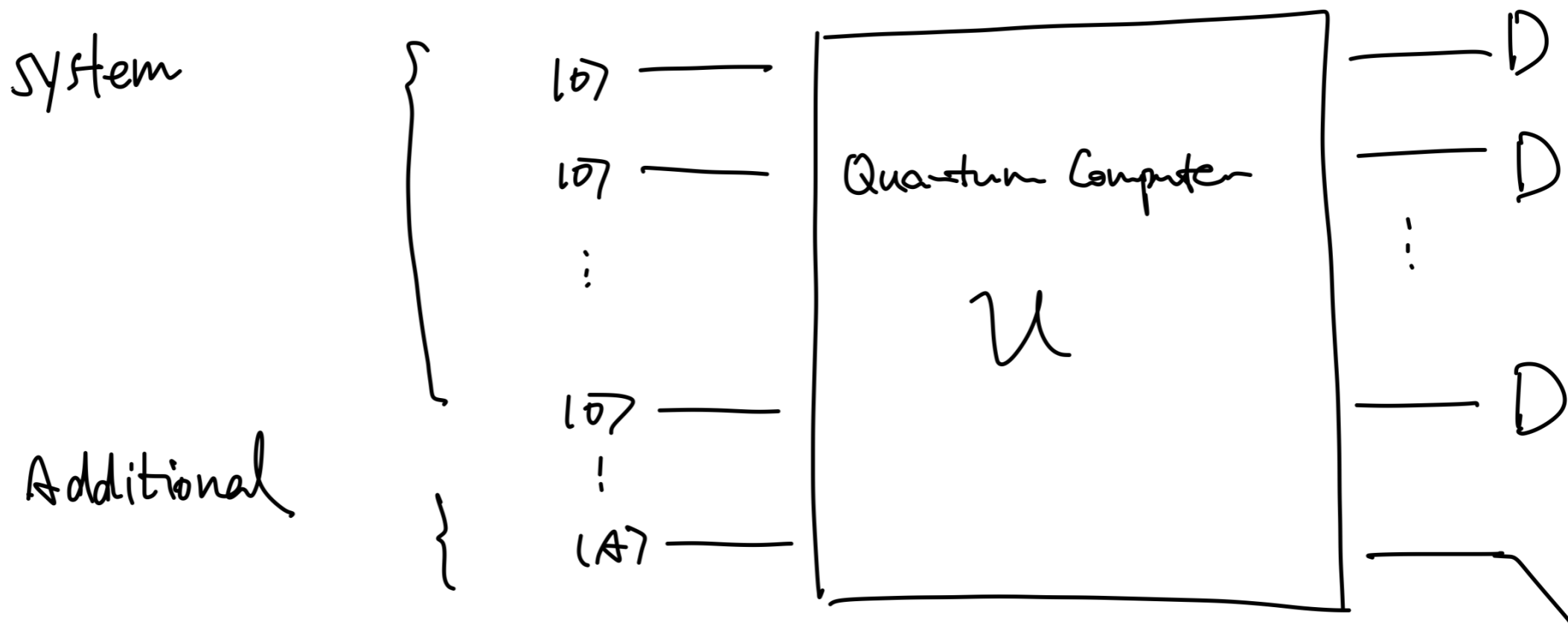
$$| \psi \rangle : \quad i \partial_t | \psi \rangle = H | \psi \rangle$$

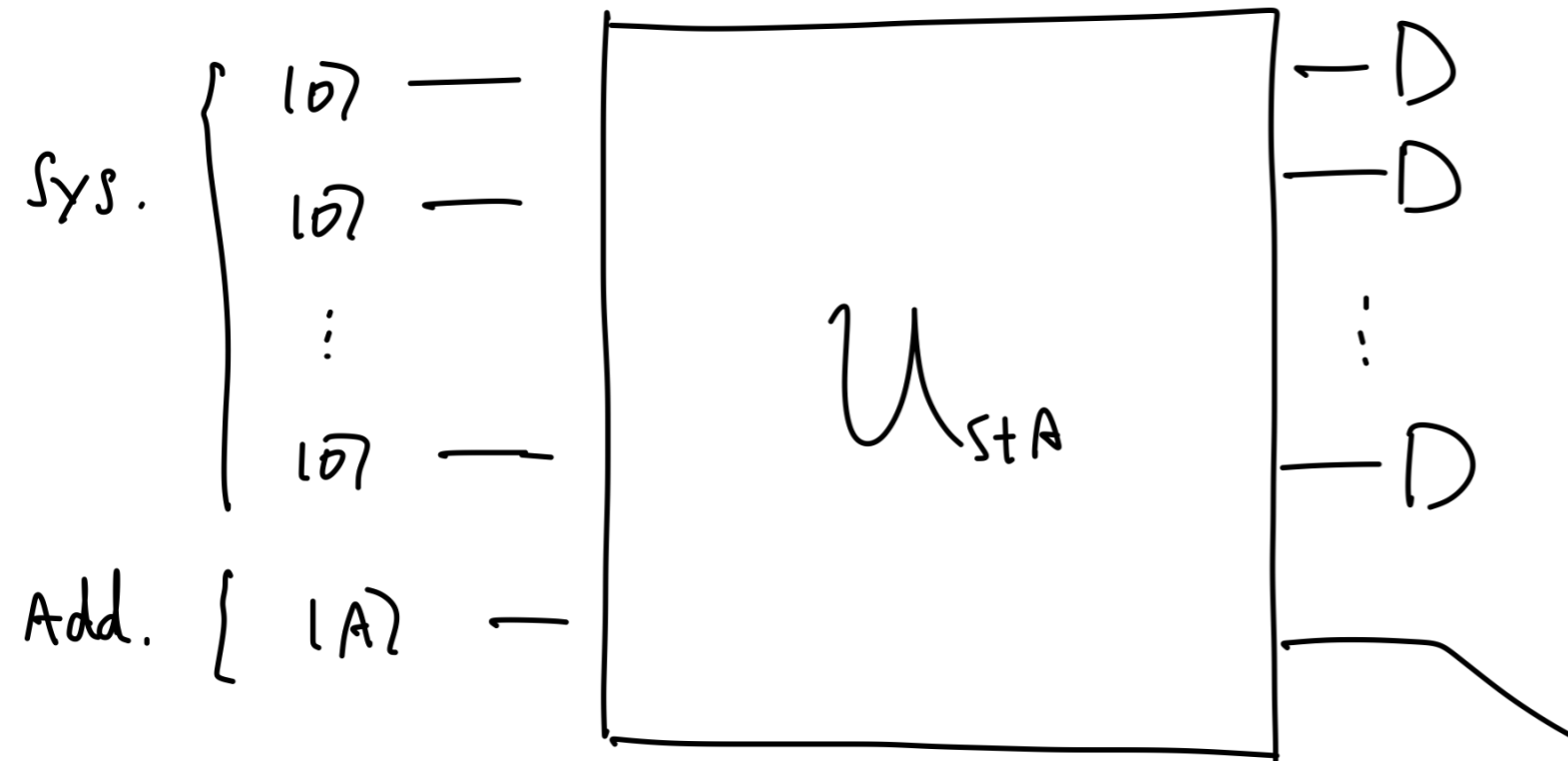
$$U = e^{-i H t} \quad H : \text{Hamiltonian}$$

$$\rho : \quad \partial_t \rho(t) = -i [H(t), \rho(t)]$$

von Neumann eq.

Quantum Computation



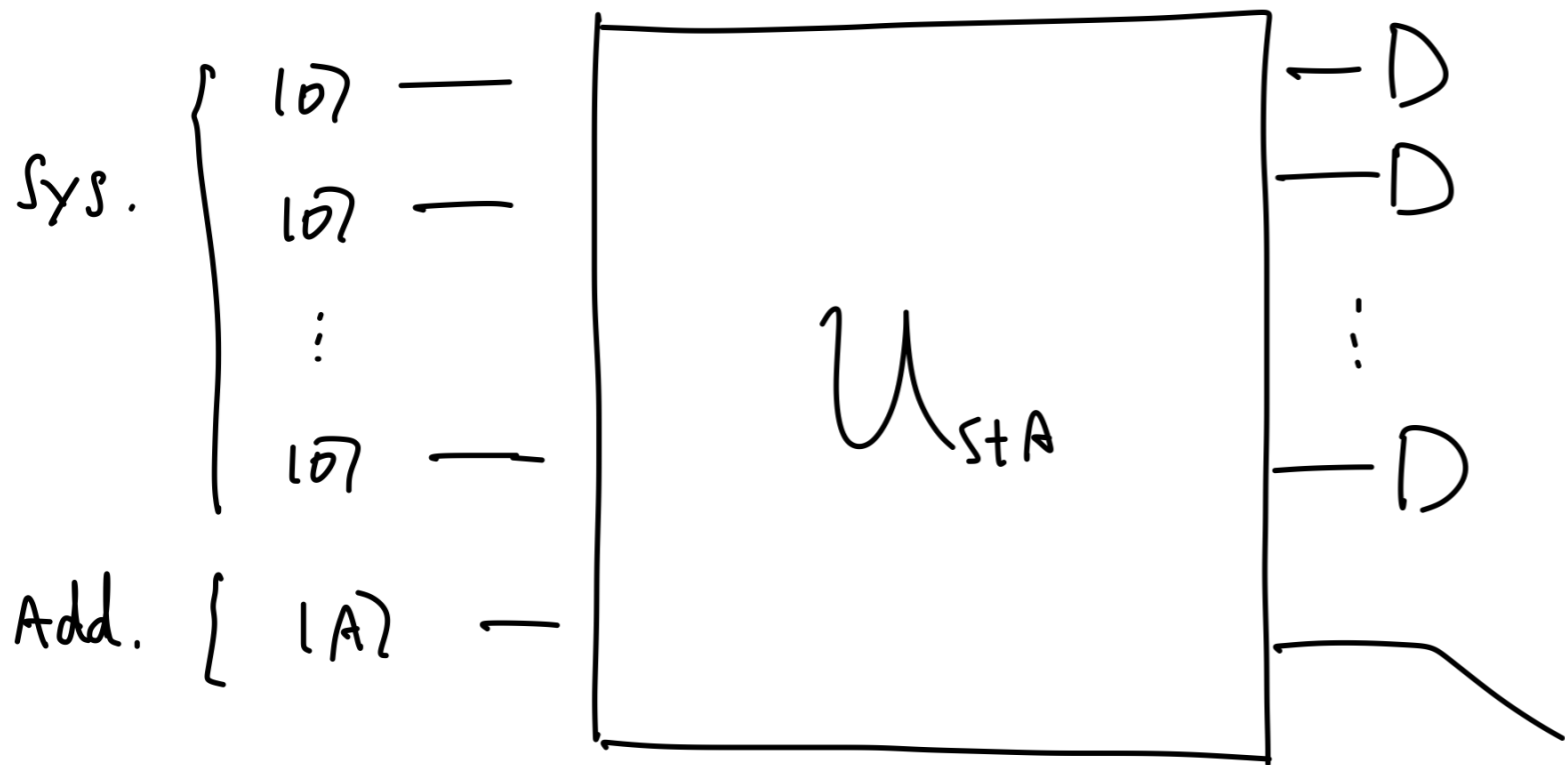


Dynamics of system qubits may not be unitary

$$U_{SA} \rho_S \otimes \rho_A U_{SA}^\dagger$$

discard A
 \swarrow tr : mathematical description of a measurement

$$\text{tr}_A U_{SA} \rho_S \otimes \rho_A U_{SA}^\dagger$$



Dynamics of S : $\Sigma(\rho_S) = \text{tr}_A U_{S+A} \rho_S \otimes |e\rangle\langle e| U_{S+A}^\dagger$

$= \sum_a \langle a| U_{S+A} \rho_S \otimes |e\rangle\langle e| U_{S+A}^\dagger |a\rangle$

$= \sum_p \langle a| U_{S+A} |e\rangle \rho_S \langle e| U_{S+A}^\dagger |a\rangle$

$$\Sigma(\rho_S) = \sum_p K_p \rho_S K_p^\dagger$$

$K_p = \langle a| U_{S+A} |e\rangle$: Kraus operators

$$\sum_p K_p^\dagger K_p = \sum_p \langle e| U_{S+A}^\dagger |a\rangle \langle a| U_{S+A} |e\rangle = I_S$$

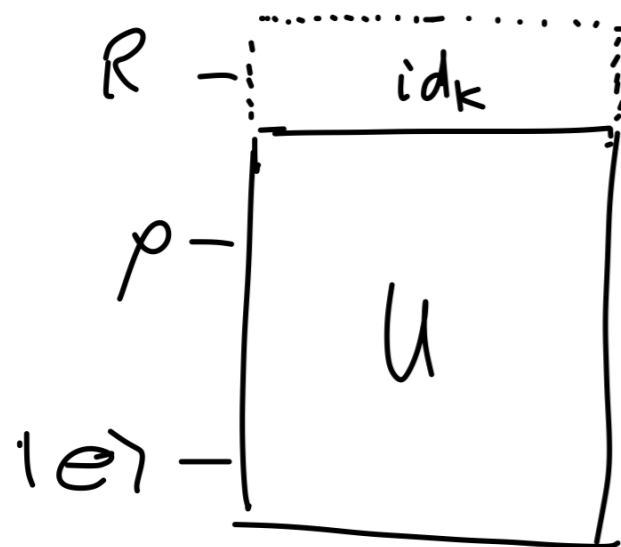
$$\Sigma(\rho) = \sum_a K_a \rho K_a^\dagger \quad : \quad \begin{array}{l} \text{a quantum channel} \\ \text{a dynamical map} \end{array}$$

a dynamical map $\rho(t+dt) = V(t) \rho(t)$, $V(t) = e^{Lt}$

L : Lindblad generator c.f. $U = e^{-iHt}$

open problem: $\Sigma \sim L$?

$$\Sigma \geq 0 \quad \text{if } \forall \rho \geq 0, \Sigma(\rho) \geq 0$$



$$\begin{array}{l} - \quad id_k \\ - \quad \Sigma \end{array}$$

$$\begin{array}{l} \Sigma \geq 0 \quad : \quad \Sigma \text{ positive} \\ \forall_k, id_k \otimes \Sigma \geq 0 \quad : \quad \Sigma \text{ completely} \\ \text{positive (CP)} \end{array}$$

A general description of a quantum dynamics

- Λ is a quantum channel .

$$\Lambda \succeq 0, \quad \text{id} \otimes \Lambda \succeq 0$$

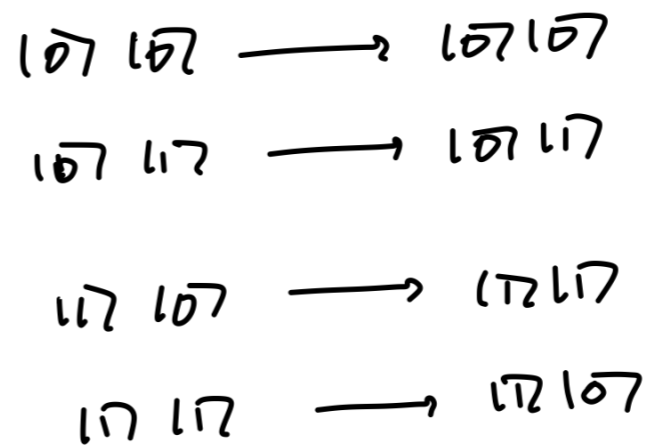
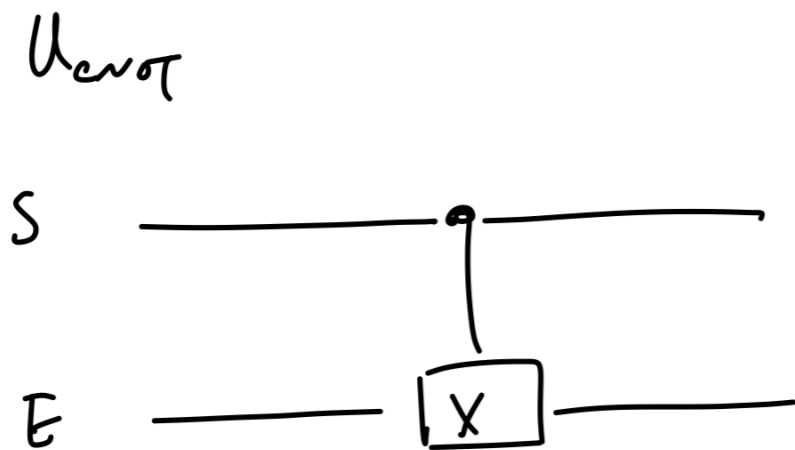
- $\Lambda \sim \{K_a\}, \quad \Lambda(\rho) = \sum_a K_a \rho K_a^\dagger$

- $\Lambda(\rho) = \text{tr}_A U_{SA} \rho \otimes |e\rangle\langle e| U_{SA}^\dagger = V \rho V^\dagger$

V : isometry

- a dynamical map, \mathcal{L} .

Example



$$\begin{aligned}
 U &= |00\rangle\langle 00| + |01\rangle\langle 01| + |10\rangle\langle 11| + |11\rangle\langle 10| \\
 &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} = |0\rangle\langle 0| \otimes I + |1\rangle\langle 1| \otimes X
 \end{aligned}$$

$$\rho_S(t) = \text{tr}_E U_{env} \rho \otimes |0\rangle\langle 0| U_{env}^\dagger +$$

$$= \text{tr}_E \langle 0| U_{env} \rho \otimes |0\rangle\langle 0| U_{env}^\dagger |0\rangle_E + \text{tr}_E \langle 1| U_{env} \rho \otimes |0\rangle\langle 0| U_{env}^\dagger |1\rangle_E$$

$$= \text{tr}_E \langle 0| U_{env} |0\rangle_E \rho \text{tr}_E \langle 0| U_{env}^\dagger |0\rangle_E + \text{tr}_E \langle 1| U_{env} |0\rangle_E \rho \text{tr}_E \langle 0| U_{env}^\dagger |1\rangle$$

$$\rho_S(t) = \text{tr}_E U_{cnv} \rho \otimes |0\rangle\langle 0| U_{cnv}^\dagger$$

$$= \underbrace{\langle 0| U_{cnv}}_E \rho \otimes |0\rangle\langle 0| U_{cnv}^\dagger |0\rangle_E + \underbrace{\langle 1| U_{cnv}}_E \rho \otimes |0\rangle\langle 0| U_{cnv}^\dagger |1\rangle_E$$

$$= \underbrace{\langle 0| U_{cnv}}_E |0\rangle_E \rho \langle 0| U_{cnv}^\dagger |0\rangle_E + \underbrace{\langle 1| U_{cnv}}_E |0\rangle_E \rho \langle 0| U_{cnv}^\dagger |1\rangle_E$$

$$\rho_S(t) = K_0 \rho K_0^\dagger + K_1 \rho K_1^\dagger$$

$$K_0^\dagger K_0 + K_1^\dagger K_1 = \langle 0| U_{cnv}}_E^\dagger \langle 0| U_{cnv}}_E + \langle 0| U_{cnv}}_E^\dagger |1\rangle_E \langle 1| U_{cnv}}_E$$

$$= \langle 0| U_{cnv}}_E^\dagger \underbrace{(|0\rangle\langle 0| + |1\rangle\langle 1|)}_{I_E} U_{cnv}}_E |0\rangle_E$$

$$= \langle 0| \underbrace{U_{cnv}}_E^\dagger U_{cnv}}_E |0\rangle_E = I_S$$

A fundamental operational task : distinguishability

Problem statement

Suppose that ρ_1 is given with a priori prob $\frac{1}{2}$

ρ_2 is given with a priori prob $\frac{1}{2}$

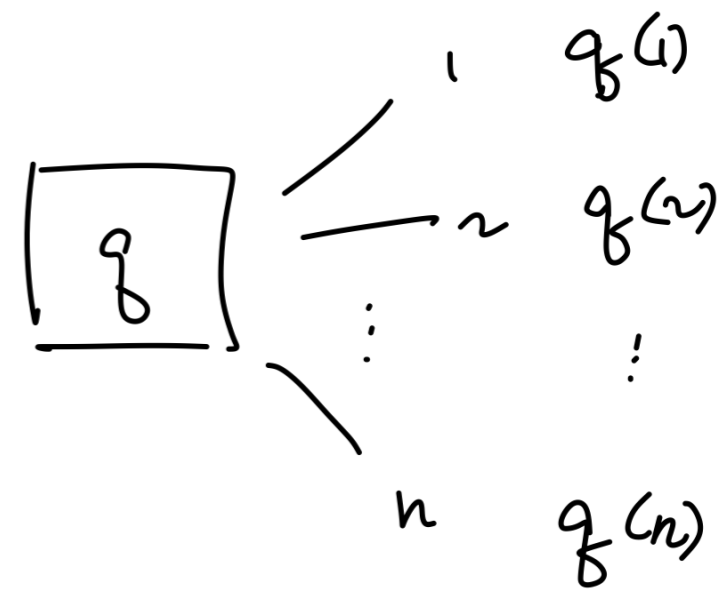
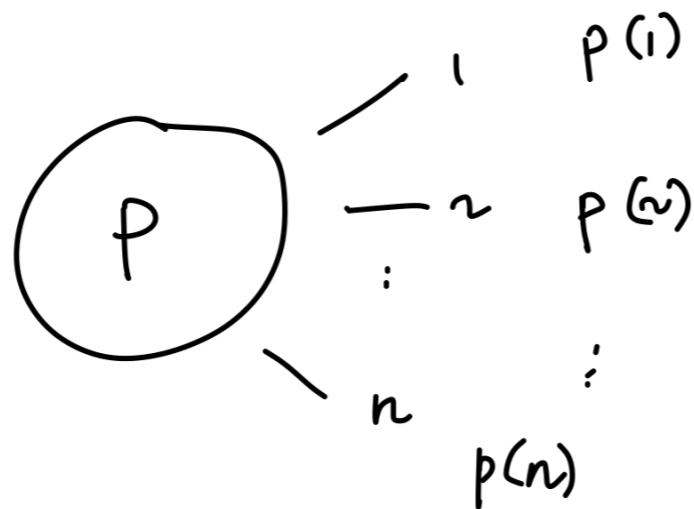
A measurement is given, you can optimize it.

Find the highest probability you make a correct guess

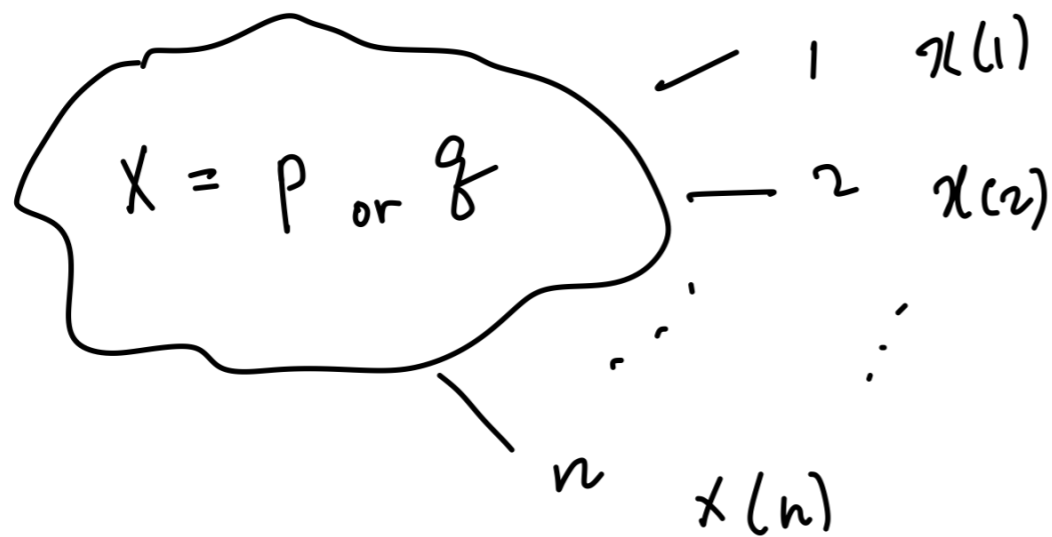
& an optimal measurement that achieves the guessing probability.

In a classical scenario

two probabilistic systems

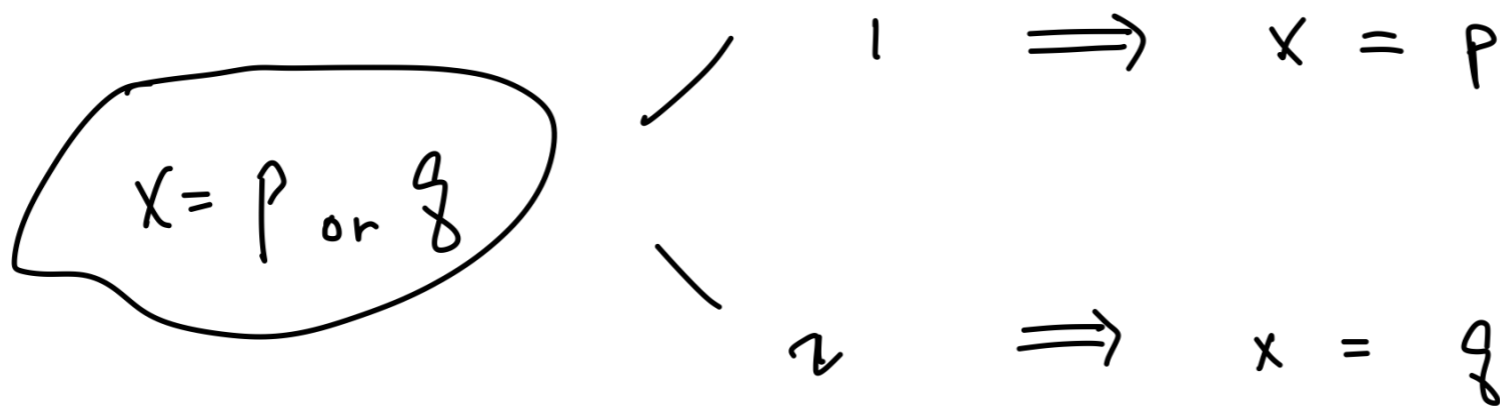
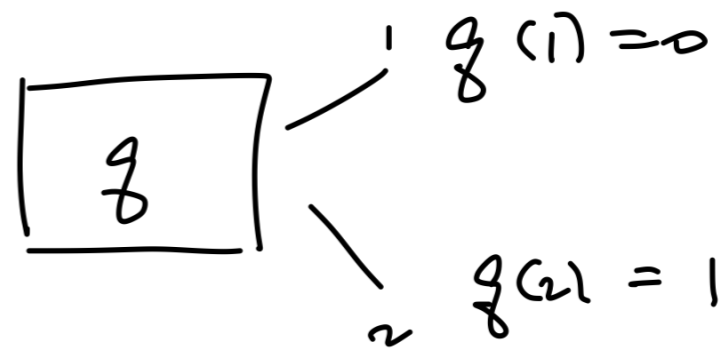
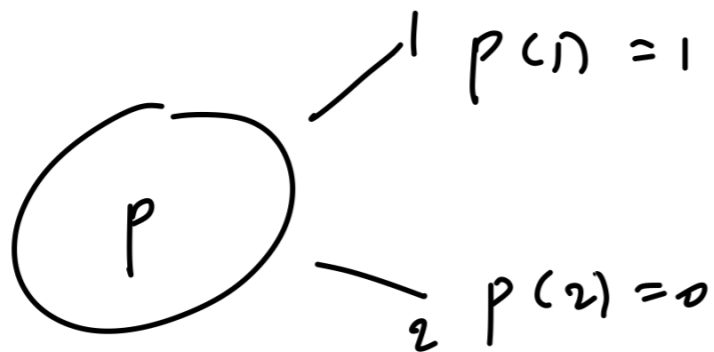


Given



find $X = P$ or $X = Q$?

e.g.



What is the optimal strategy to distinguish two probabilistic systems?

$$D(p, q) = \frac{1}{2} \sum_{x \in X} |p_x(x) - q_x(x)| \quad : \text{variational distance}$$

$$P_{\text{guess}} = \max_{S: \text{strategy}} \frac{1}{2} \text{Prob}[S = p | p] + \frac{1}{2} \text{Prob}[S = q | q]$$

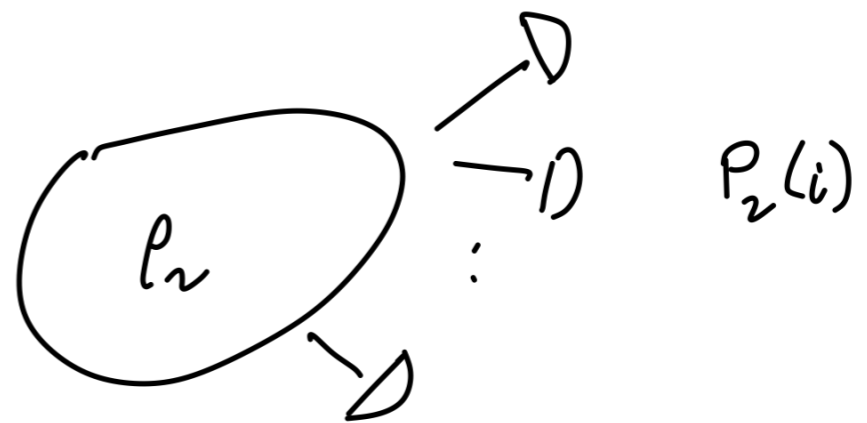
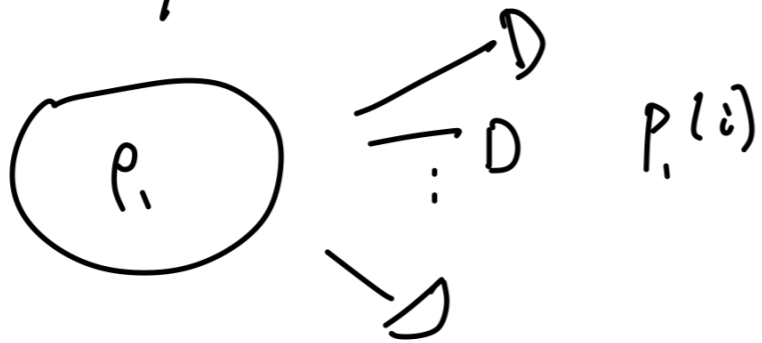
$$= \frac{1}{2} + \frac{1}{2} D(p, q) \quad : \text{operational meaning of } d(p, q)$$

two probabilistic systems



$$P_{\text{guess}} = \frac{1}{2} + \frac{1}{2} \delta(p, q)$$

two quantum systems



$$P_{\text{guess}} = \max_{M: \text{POVM}} \frac{1}{2} \text{Prob}_M [S = P_1 | P_1] + \frac{1}{2} \text{Prob}_M [S = P_2 | P_2]$$

S : Strategy

$$= \frac{1}{2} + \frac{1}{2} D(P_1, P_2)$$

$$D(P_1, P_2) = \frac{1}{2} \|P_1 - P_2\|_1, \quad \|A\|_1 = \text{tr} \sqrt{A^\dagger A} = \sum_i |\text{eig}(A)|$$

Problem statement

Suppose that ρ_1 is given with a priori prob $\frac{1}{2}$

ρ_2 is given with a priori prob $\frac{1}{2}$

A measurement is given, you can optimize it.

Find the highest probability you make a correct guess

& an optimal measurement that achieves the guessing probability.

$$P_{\text{guess}} = \frac{1}{2} + \frac{1}{2} D(\rho_1, \rho_2), \quad D(\rho_1, \rho_2) = \frac{1}{2} \|\rho_1 - \rho_2\|$$

opt $M \sim (\rho_1 - \rho_2)_{\pm}$, positive & negative projections

II. Quantum Computation

Quantum computation contains

- i) preparation of quantum states
- ii) dynamics
- iii) measurements

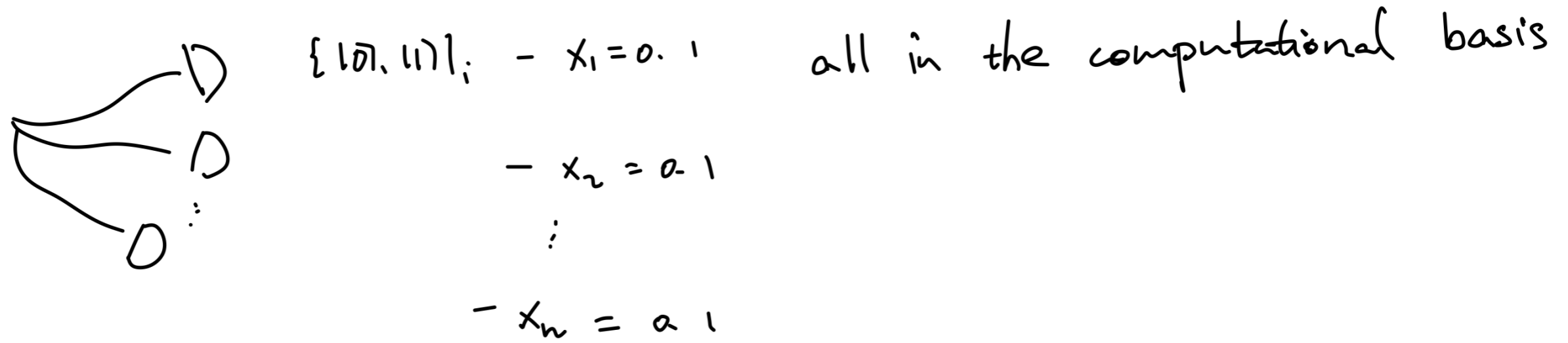
- Preparation of quantum states

$$|0\rangle^{\otimes n} \quad \text{or} \quad |L\rangle = \left[\bigotimes_{i=1}^n U_i \right] |0\rangle^{\otimes n} = U_1 |0\rangle \otimes \dots \otimes U_n |0\rangle$$

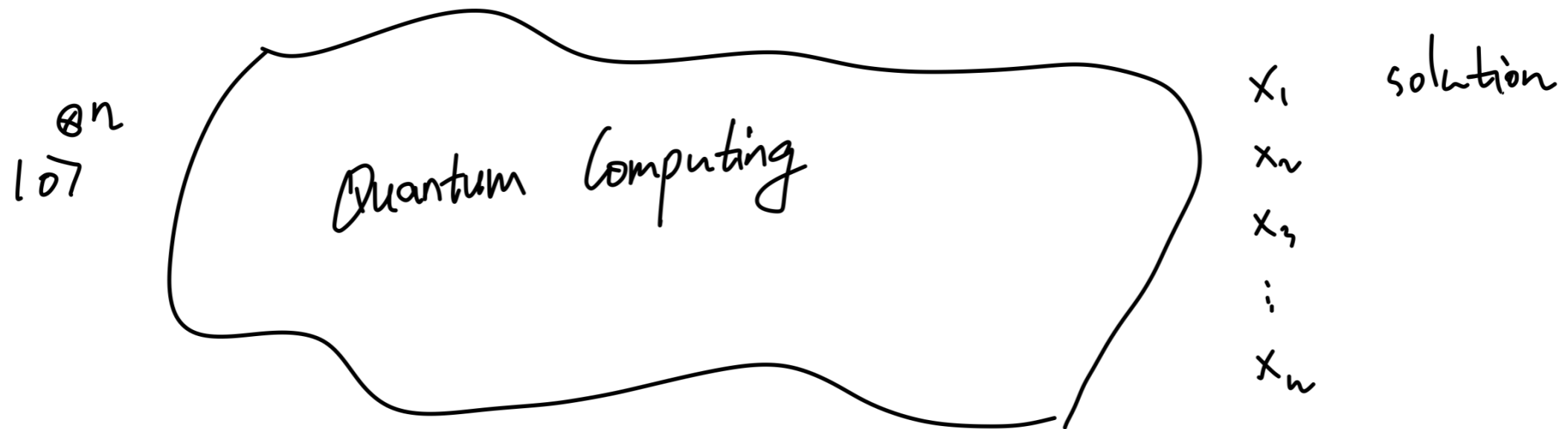
$|0\rangle^{\otimes n}$ and $|L\rangle$ are equivalent up to local unitary transformations.

- Measurement

$$\mathcal{M} = \{ |0\rangle, |1\rangle \} \otimes \{ |0\rangle, |1\rangle \} \otimes \dots \otimes \{ |0\rangle, |1\rangle \}_n$$

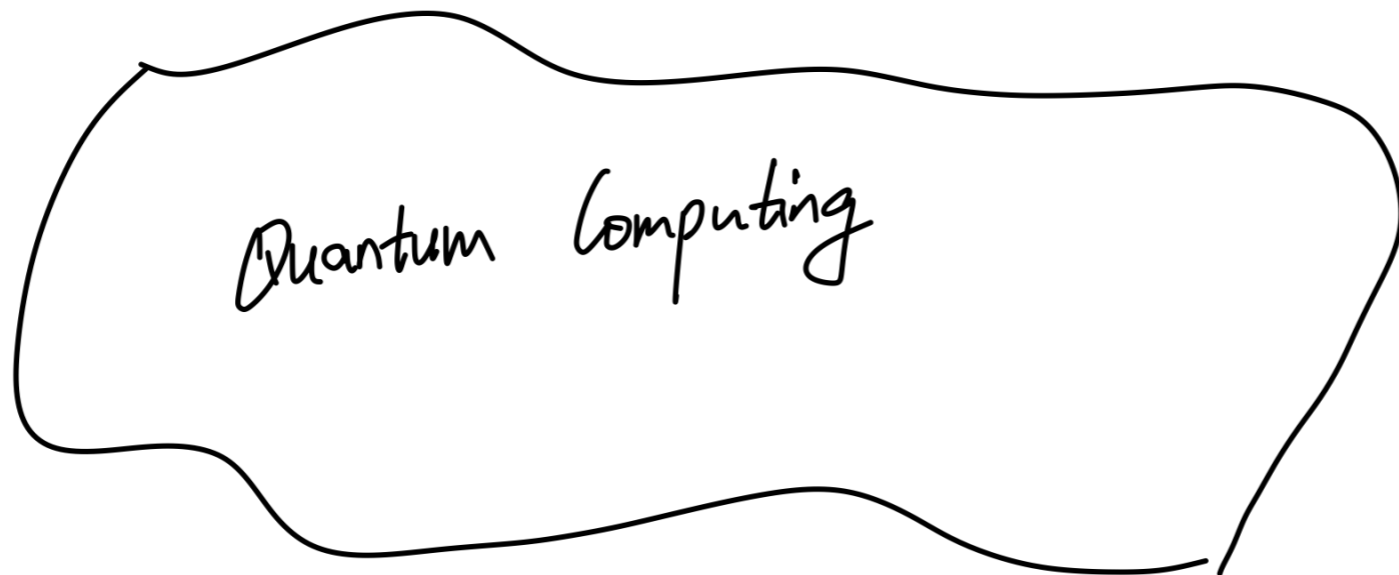


- dynamics ~ hybrid quantum and classical operations
 ~ manipulation of quantum states



Dynamics in a quantum computer

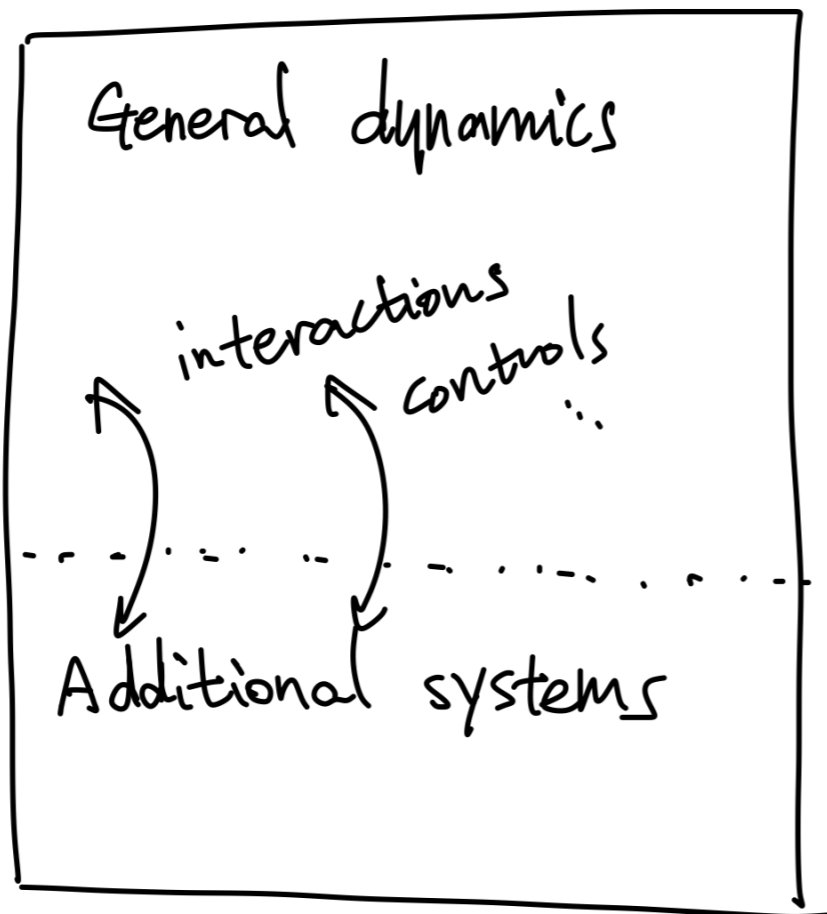
\otimes^n
 $|0\rangle$



x_1 solution
 x_2
 x_3
 \vdots
 x_n

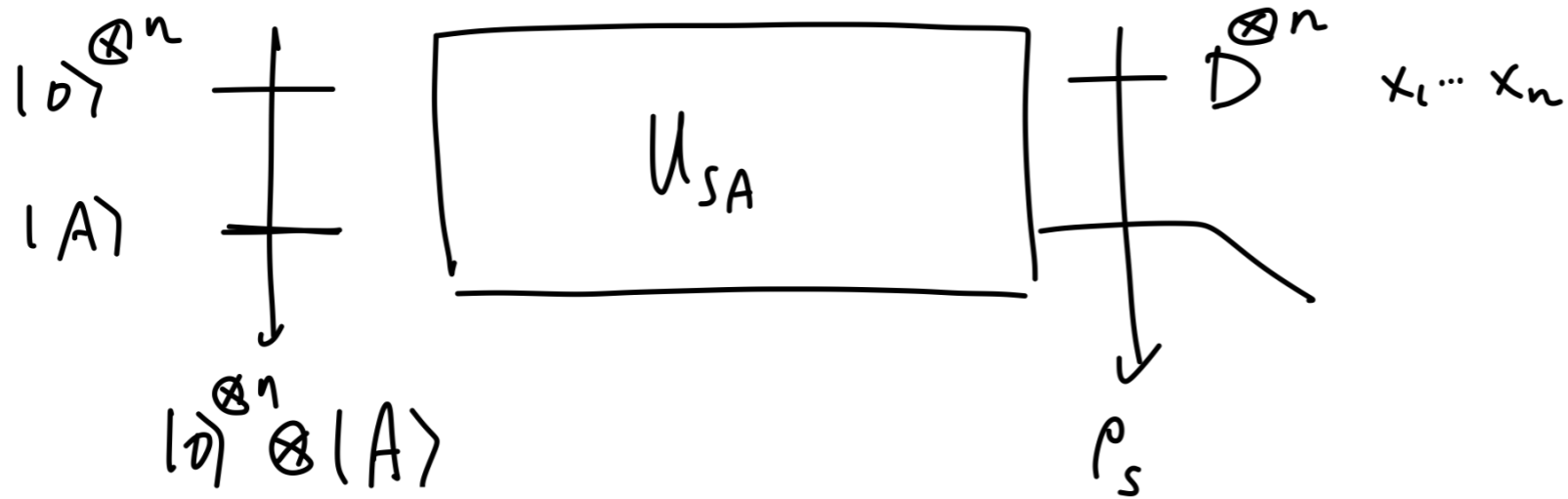
Implementation

$|0\rangle$ —
 $|0\rangle$ —
 \vdots
 $|0\rangle$ —
.....
 $|A\rangle$ —
 \vdots
 $|A\rangle$ —



— D — x_1
— D — x_2
 \vdots
— D — x_n
.....
.....
.....

} measurement outcomes



dynamics : $\text{tr}_A U_{SA} |0\rangle^{\otimes n} \otimes |A\rangle U_{SA}^\dagger = \rho_S$

measurement : $\text{tr} [M_{x_1} \otimes M_{x_2} \otimes \dots \otimes M_{x_n} \rho_S] = p(x_1 \dots x_n | \rho_S)$

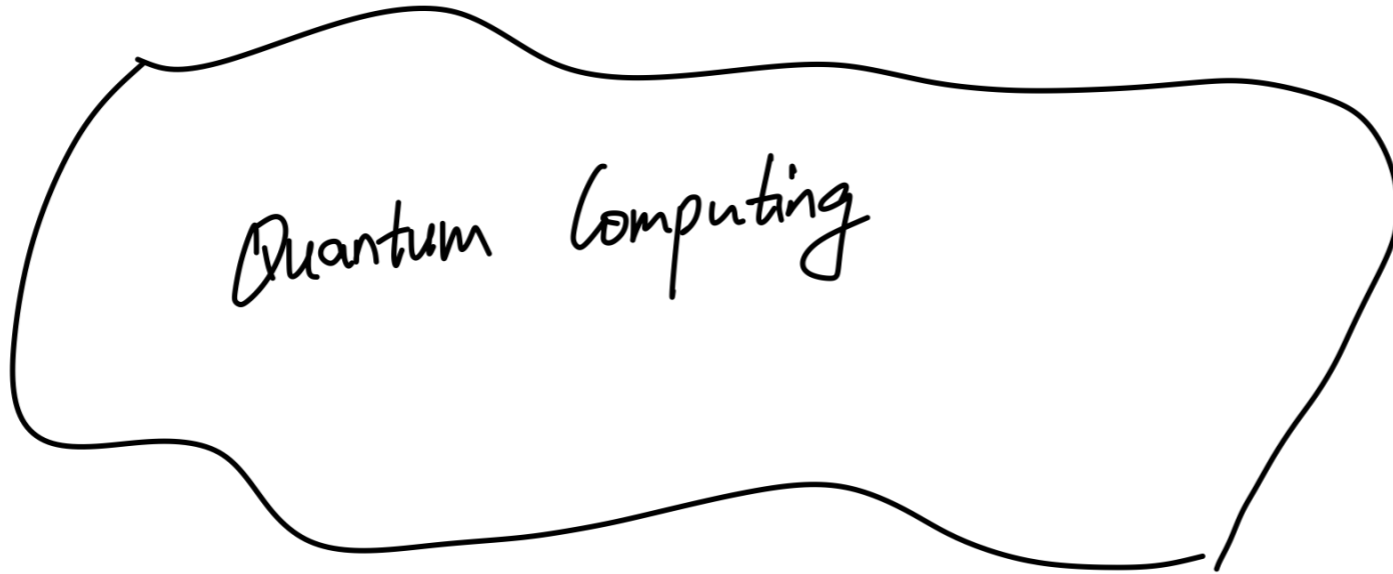
$x^n = x_1 x_2 \dots x_n$ is obtained with probability

$\text{tr} [M_{x_1} \otimes M_{x_2} \otimes \dots \otimes M_{x_n} \otimes I_A U_{SA} |0\rangle^{\otimes n} \otimes |A\rangle U_{SA}^\dagger]$

solutions of a mathematical problem

resources for computation

$107^{\otimes n}$



x_1 solution
 x_2
 x_3
 \vdots
 x_n

$x^n = x_1 x_2 \dots x_n$ is obtained with probability

$$\text{tr} \left[M_{x_1} \otimes M_{x_2} \otimes \dots \otimes M_{x_n} \otimes I_A U_{SA} \underbrace{|0\rangle^{\otimes n}} \otimes \underbrace{|A\rangle} U_{SA}^\dagger \right]$$

↓
 solutions of a mathematical problem

resources for computation

U_{SA} and $|A\rangle$ are designed such that the solution of a mathematical problem is provided by x^n with finite resources (time, space, ...)

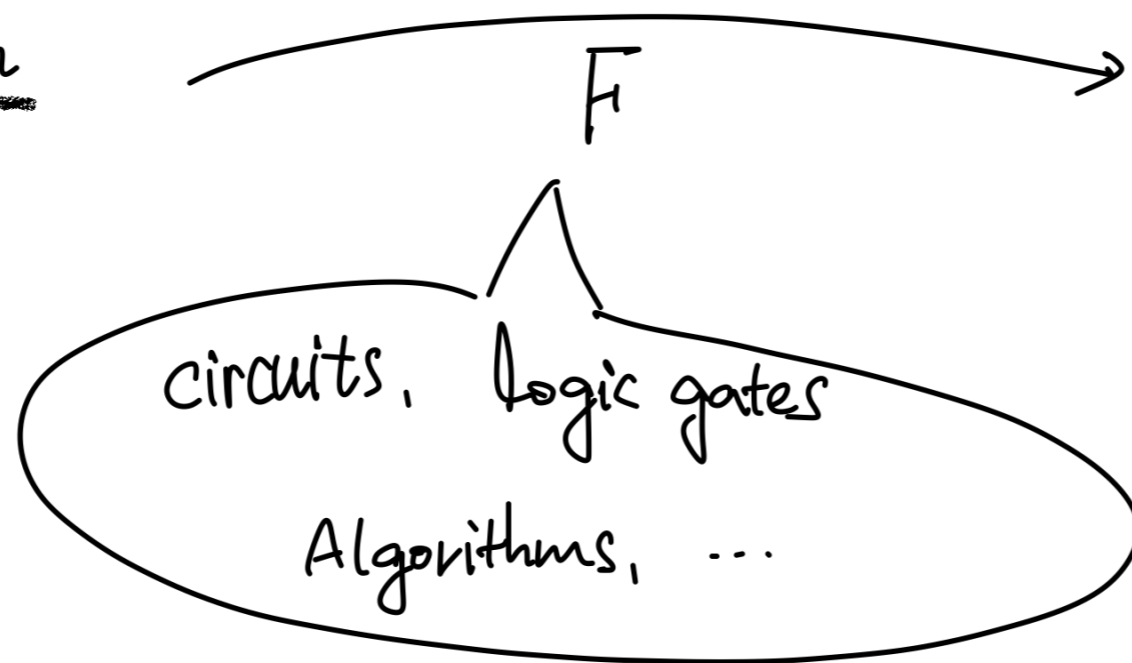
The main question to apply quantum theory to a computational task

X : a mathematical problem to solve

$x^n = x_1 x_2 \dots x_n$ is a solution

F denotes a set of steps to find x^n , an algorithm

$i^n = i_1 \dots i_n$
trivial input



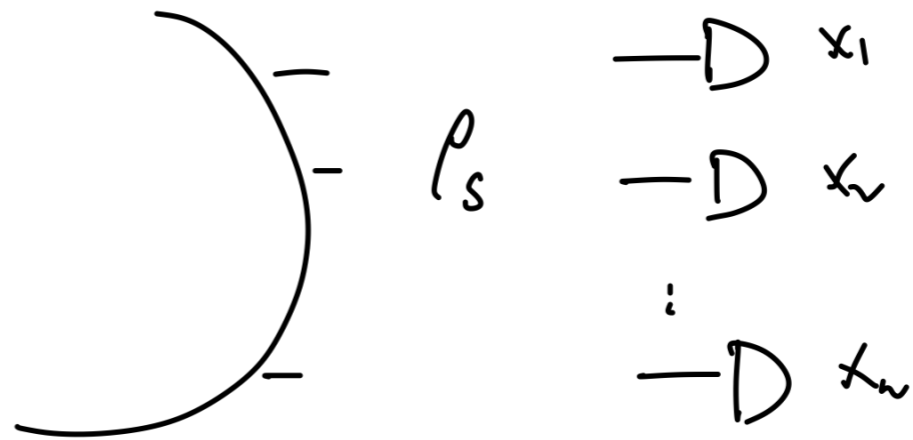
$F[x] \in \{0,1\}^n$
meaningful output

$$\delta(F[x], x^n) < \epsilon \quad \forall \epsilon > 0$$

(\Leftrightarrow) F solves the problem

Design quantum steps to solve a mathematical problem

$$F_Q \sim \text{tr} \left[M_{x_1} \otimes \dots \otimes M_{x_n} \otimes I_A U_{SA} |0\rangle\langle 0|^{\otimes n} \otimes |A\rangle\langle A| U_{SA}^\dagger \right]$$



ρ_S such that

$$D \left[|x^n\rangle\langle x^n|, \text{tr}_A U_{SA} |0\rangle\langle 0|^{\otimes n} \otimes |A\rangle\langle A| U_{SA}^\dagger \right] < \epsilon$$

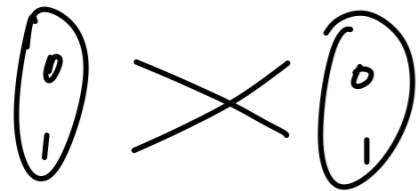
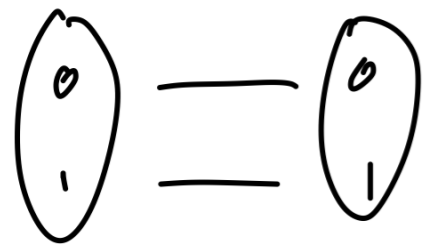
$|0\rangle^{\otimes n}$



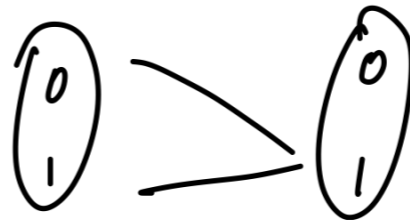
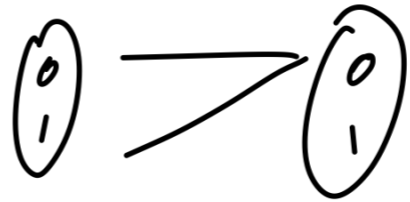
~ state transformation
state manipulation

The Deutsch Problem

$$f : \{0,1\} \rightarrow \{0,1\}$$



1-1 function
(balanced function)



constant function

Problem : Given a function $f : \{0,1\} \rightarrow \{0,1\}$

determine if f is constant or balanced.

classical solution : call $f(x)$ twice

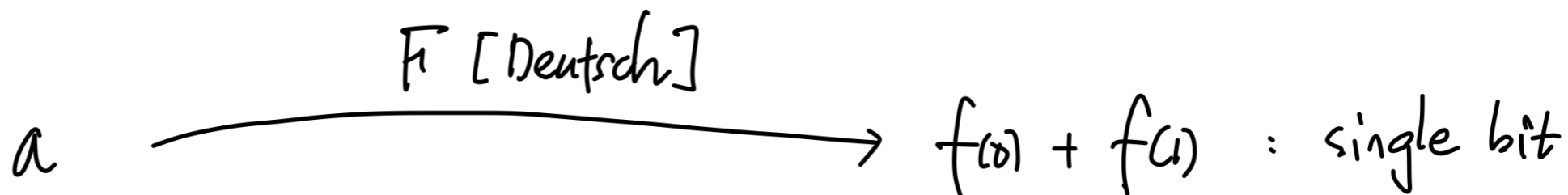
quantum solution : call $f(x)$ once ✓

Problem : Given a function $f: \{0,1\} \rightarrow \{0,1\}$

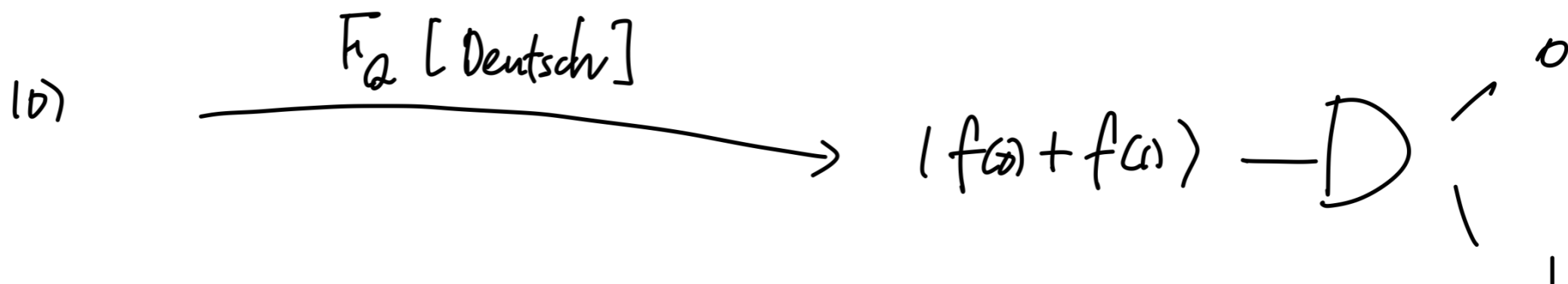
determine if f is constant or balanced.

$$\iff \text{Find } f(0) + f(1) = \begin{cases} 0 & \text{iff } f \text{ is constant} \\ 1 & \text{iff } f \text{ is balanced} \end{cases}$$

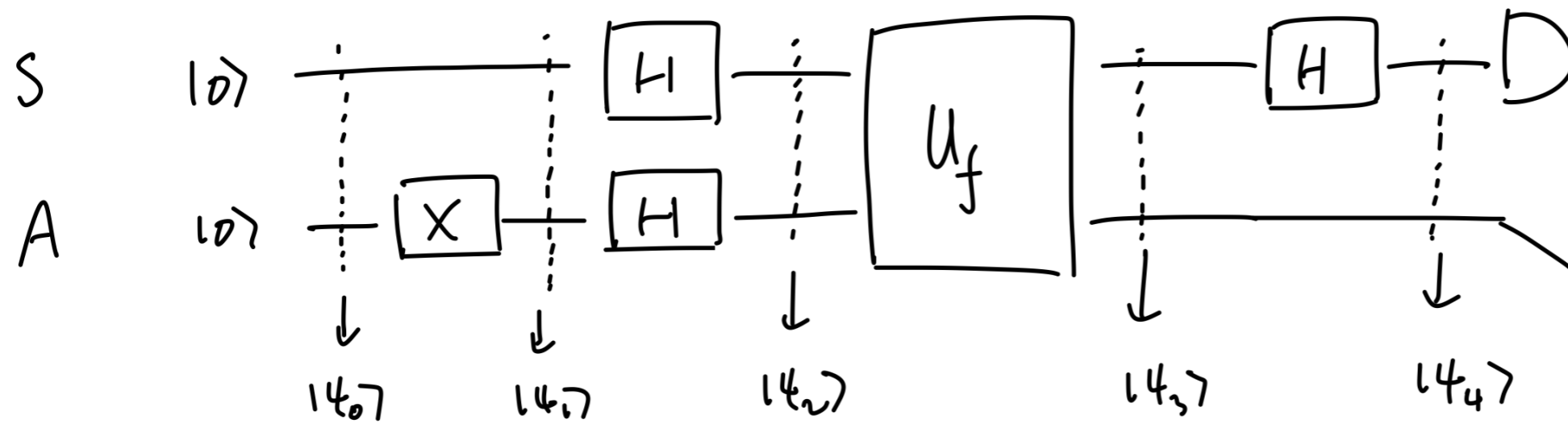
Classical



Quantum



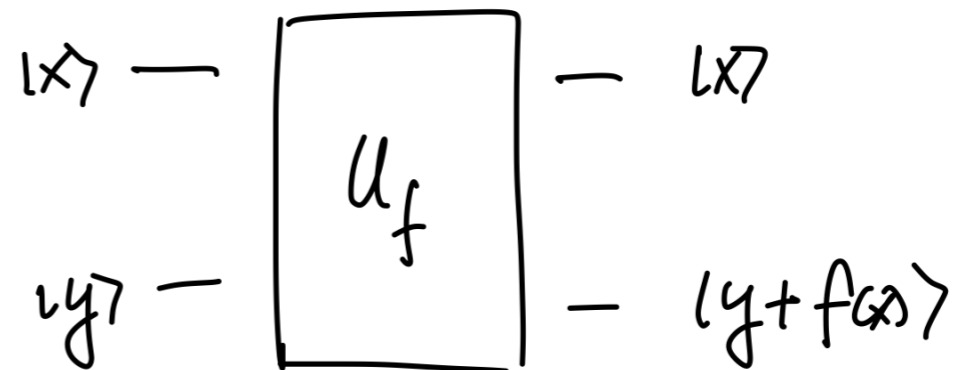
The Deutsch Algorithm



note. $H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ $H|0\rangle = |+\rangle = \frac{1}{\sqrt{2}} (|+\rangle + |-\rangle)$ Hadamard gate
 $H|1\rangle = |-\rangle = \frac{1}{\sqrt{2}} (|+\rangle - |-\rangle)$

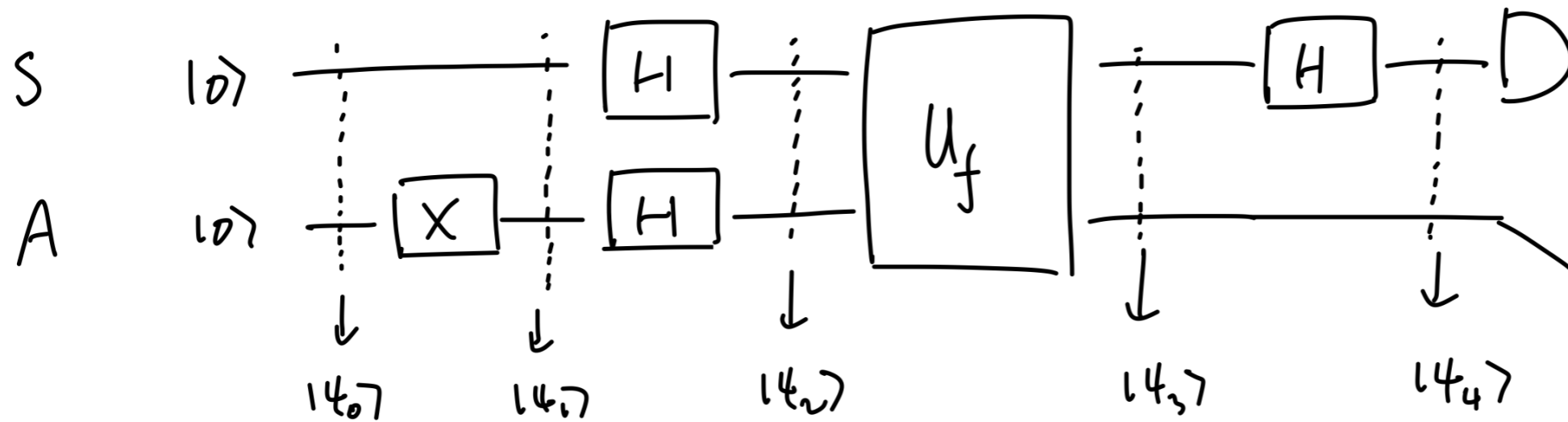
$$U_f |x\rangle |y\rangle = |x\rangle |y + f(x)\rangle$$

note. U_f is unitary
 proof. (exercise)



$$U_f = \sum_{x,y} |x\rangle\langle x| \otimes |y + f(x)\rangle\langle y|$$

The Deutsch Algorithm



$$|\psi_0\rangle = |0\rangle_S |0\rangle_A$$

$$|\psi_1\rangle = |0\rangle |1\rangle$$

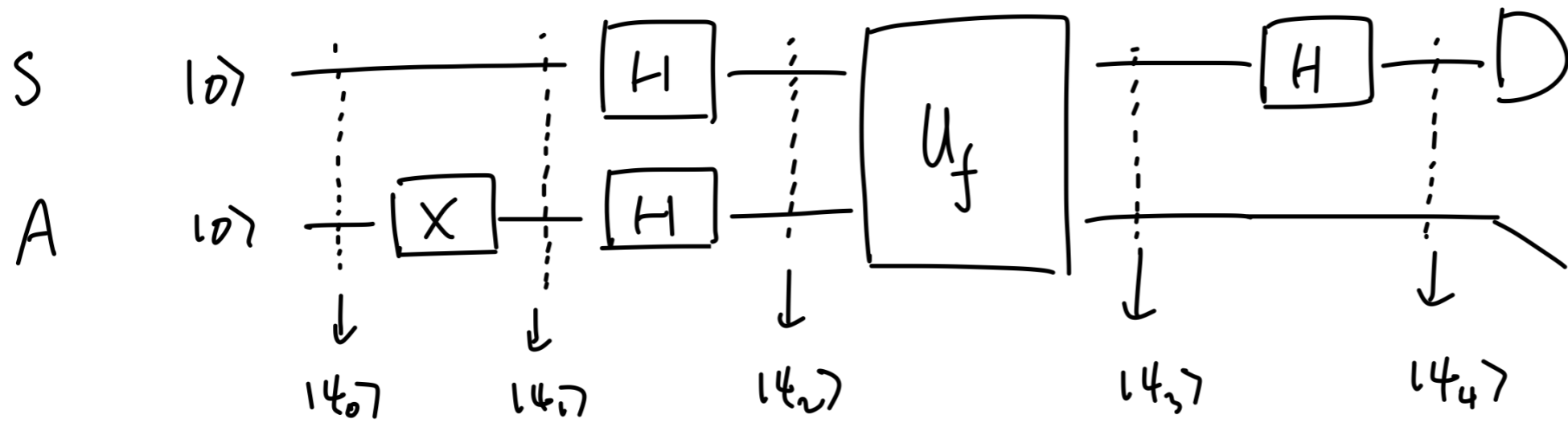
$$|\psi_2\rangle = |+\rangle |-\rangle = \frac{1}{\sqrt{2}} |0\rangle |-\rangle + \frac{1}{\sqrt{2}} |1\rangle |-\rangle$$

note. $U_f |x\rangle |-\rangle = U_f \left(|x\rangle \frac{1}{\sqrt{2}} |0\rangle - |x\rangle \frac{1}{\sqrt{2}} |1\rangle \right)$

$$= \frac{1}{\sqrt{2}} |x\rangle |f(x)\rangle - \frac{1}{\sqrt{2}} |x\rangle |1+f(x)\rangle$$

$$= \begin{cases} |x\rangle |-\rangle & \text{if } f(x) = 0 \\ (-1) |x\rangle |-\rangle & \text{if } f(x) = 1 \end{cases} = (-1)^{f(x)} |x\rangle |-\rangle$$

The Deutsch Algorithm



$$|\psi_0\rangle = |0\rangle_S |0\rangle_A$$

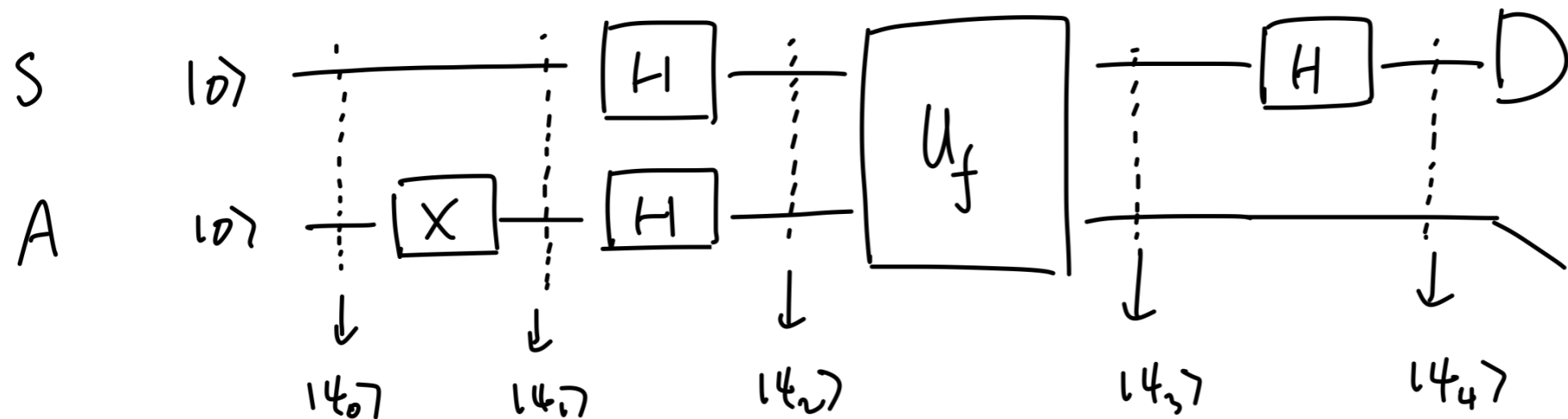
$$|\psi_1\rangle = |0\rangle |1\rangle$$

$$|\psi_2\rangle = |+\rangle |-\rangle = \frac{1}{\sqrt{2}} |0\rangle |-\rangle + \frac{1}{\sqrt{2}} |1\rangle |-\rangle$$

note. $U_f |x\rangle |-\rangle = (-1)^{f(x)} |x\rangle |-\rangle$

$$\begin{aligned} |\psi_3\rangle &= U_f |\psi_2\rangle = U_f |+\rangle |-\rangle = U_f \left(\frac{1}{\sqrt{2}} |0\rangle |-\rangle + \frac{1}{\sqrt{2}} |1\rangle |-\rangle \right) \\ &= \frac{1}{\sqrt{2}} U_f |0\rangle |-\rangle + \frac{1}{\sqrt{2}} U_f |1\rangle |-\rangle = \frac{1}{\sqrt{2}} (-1)^{f(0)} |0\rangle |-\rangle + \frac{1}{\sqrt{2}} (-1)^{f(1)} |1\rangle |-\rangle \\ &= \frac{1}{\sqrt{2}} \left((-1)^{f(0)} |0\rangle + (-1)^{f(1)} |1\rangle \right) |-\rangle \end{aligned}$$

The Deutsch Algorithm



$$|\psi_0\rangle = |0\rangle_S |0\rangle_A$$

$$|\psi_1\rangle = |0\rangle |1\rangle$$

$$|\psi_2\rangle = |+\rangle |-\rangle = \frac{1}{\sqrt{2}} |0\rangle |-\rangle + \frac{1}{\sqrt{2}} |1\rangle |-\rangle$$

$$|\psi_3\rangle = \left(\frac{1}{\sqrt{2}} (-1)^{f(0)} |0\rangle + \frac{1}{\sqrt{2}} (-1)^{f(1)} |1\rangle \right) |-\rangle$$

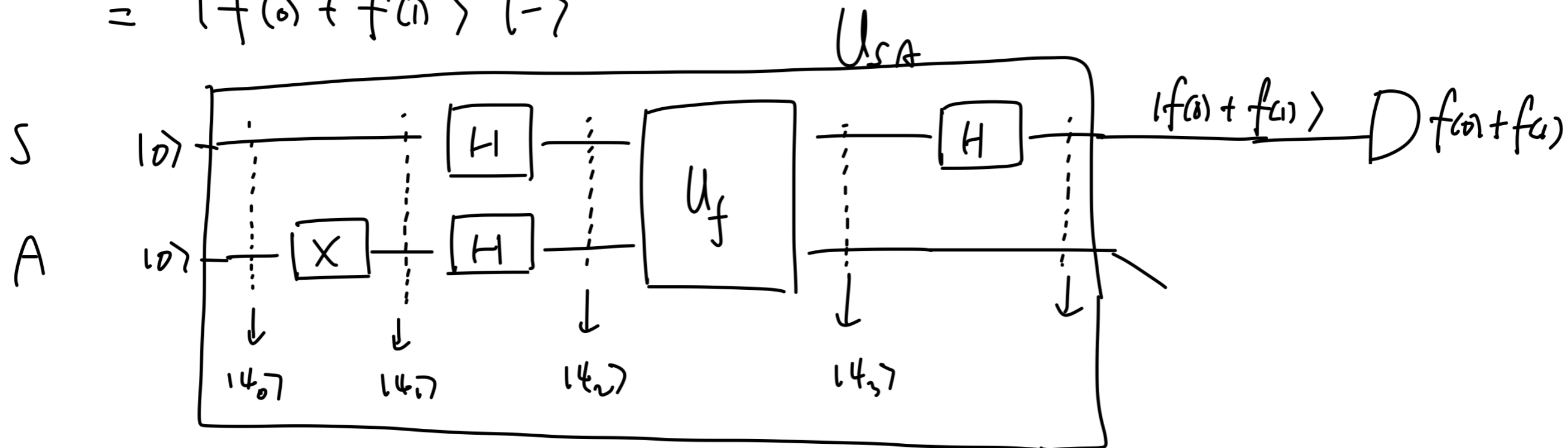
$$|\psi_4\rangle = \left(\frac{1}{\sqrt{2}} (-1)^{f(0)} |+\rangle + \frac{1}{\sqrt{2}} (-1)^{f(1)} |-\rangle \right) |-\rangle$$

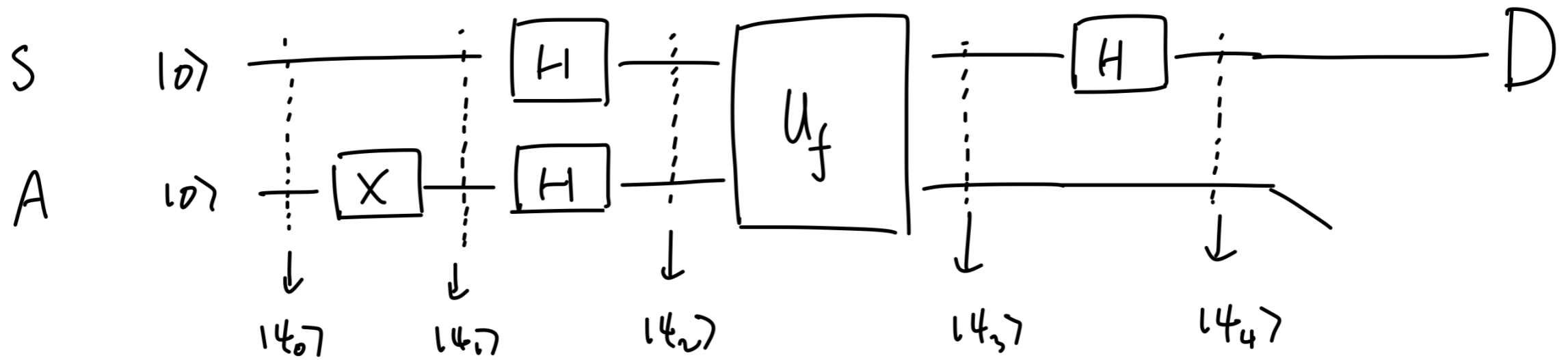
$$|4_4\rangle = \left(\frac{1}{\sqrt{2}} (-1)^{f(0)} |+\rangle + \frac{1}{\sqrt{2}} (-1)^{f(1)} |-\rangle \right) |-\rangle$$

$$= \left[\frac{1}{2} \left((-1)^{f(0)} + (-1)^{f(1)} \right) |0\rangle + \frac{1}{2} \left((-1)^{f(0)} - (-1)^{f(1)} \right) |1\rangle \right] |-\rangle$$

$$= \begin{cases} |0\rangle & \text{if } f(0) = f(1) \Leftrightarrow f(0) + f(1) = 0 \\ |1\rangle & \text{if } f(0) \neq f(1) \Leftrightarrow f(0) + f(1) = 1 \end{cases} |-\rangle$$

$$= |f(0) + f(1)\rangle |-\rangle$$





$$U_{SA} = (H \otimes I) U_f (H \otimes H) (I \otimes X)$$

$$\text{tr}_A U_{SA} |0\rangle\langle 0| \otimes |0\rangle\langle 0| U_{SA}^\dagger = |f|0\rangle + f|1\rangle X |f|0\rangle + f|1\rangle$$

$$D [|f|0\rangle + f|1\rangle, \text{tr}_A U_{SA} |0\rangle\langle 0| \otimes |0\rangle\langle 0| U_{SA}^\dagger] = 0$$

U_f is applied once!

Quantum Computing

Construct U_{SA} such that

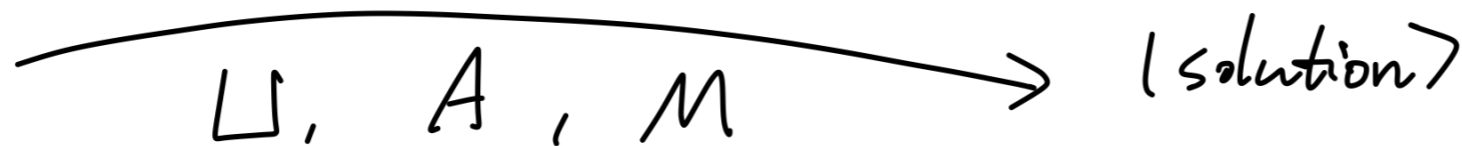
$$\sum \langle x^n, \text{tr} \underbrace{M_{x_1} \otimes M_{x_2} \otimes \dots \otimes M_{x_n} \otimes I_A}_{\text{measurement in a computational basis}} U_{SA} |0\rangle^{\otimes n} \otimes |A\rangle \langle A| U_{SA}^\dagger \rangle < \epsilon$$

\uparrow
 $f(0) + f(1)$

measurement in
 a computational basis

$$U_{SA} = (H \otimes I) U_f (H \otimes H) (I \otimes X)$$

$|0\rangle^{\otimes n}$



wordle : universal transformation

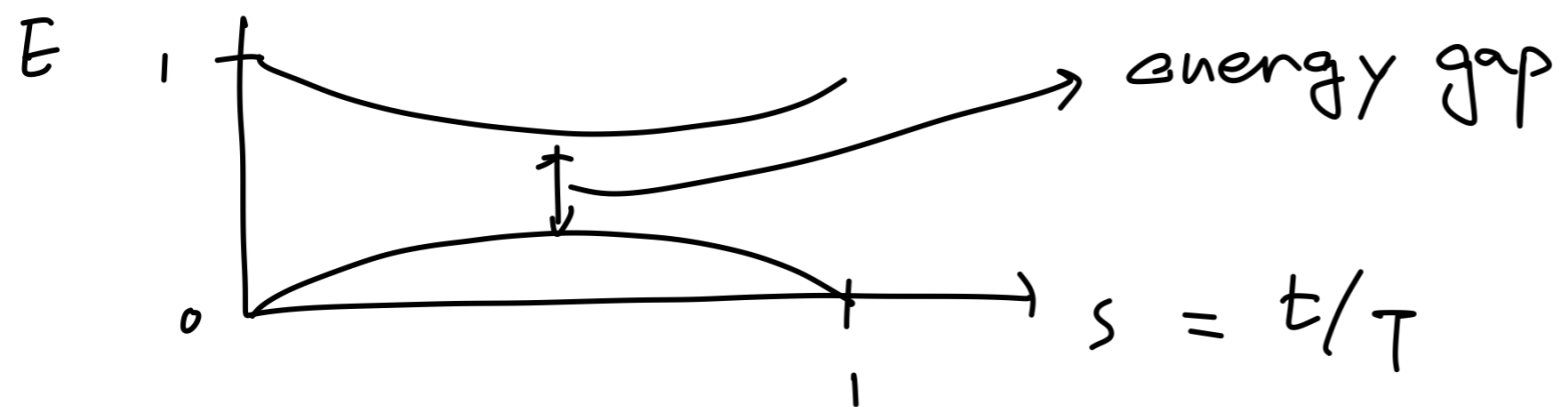
• CNOT + all single-qubit operations are universal.

• CNOT + H. T = ($\pi/8$ gate) = $\begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix}$

$$H(s) = (1-s)H_0 + sH_1 \quad s = s(t)$$

$$H_0 = \mathbb{I} - |4_0\rangle\langle 4_0| \quad : \quad \text{ground state} \quad H_0|4_0\rangle = 0 \cdot |4_0\rangle$$

$$H_1 = \mathbb{I} - |4_1\rangle\langle 4_1| \quad : \quad \text{ground state} \quad H_1|4_1\rangle = 0 \cdot |4_1\rangle$$

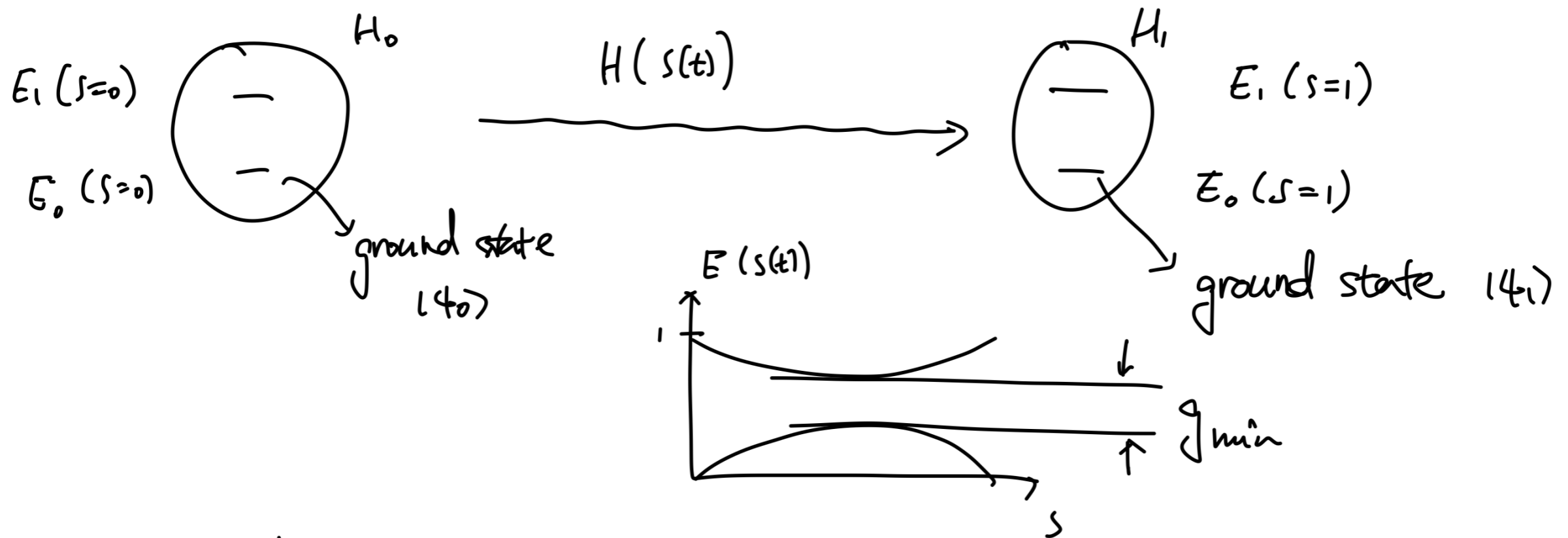


$$|4_0\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$$

$$|4_1\rangle = \alpha |0\rangle + \beta |1\rangle$$

$$f \text{ is constant} \Leftrightarrow \begin{cases} \alpha = 1 \\ \beta = 0 \end{cases} \quad \left(\begin{array}{l} \alpha = \frac{1}{2} ((-1)^{f(0)} + (-1)^{f(1)}) \\ \beta = \frac{1}{2} ((-1)^{f(0)} - (-1)^{f(1)}) \end{array} \right.$$

$$f \text{ is balanced} \Leftrightarrow \begin{cases} \alpha = 0 \\ \beta = 1 \end{cases}$$



Adiabatic theorem

$$g_{\min} = \min_{0 \leq s \leq 1} (E_1(s) - E_0(s))$$

provided that

$$\frac{1}{g_{\min}^2} \left| \left\langle \frac{dH}{dt} \right\rangle \right| \leq \epsilon, \quad \left\langle \frac{dH}{dt} \right\rangle = \langle E_1(s) | \frac{dH}{dt} | E_0(s) \rangle$$

then $|\psi_0\rangle \longrightarrow |\psi_i\rangle$ with probability $(1 - \epsilon^2)^2$

• "Adiabatic evolution"

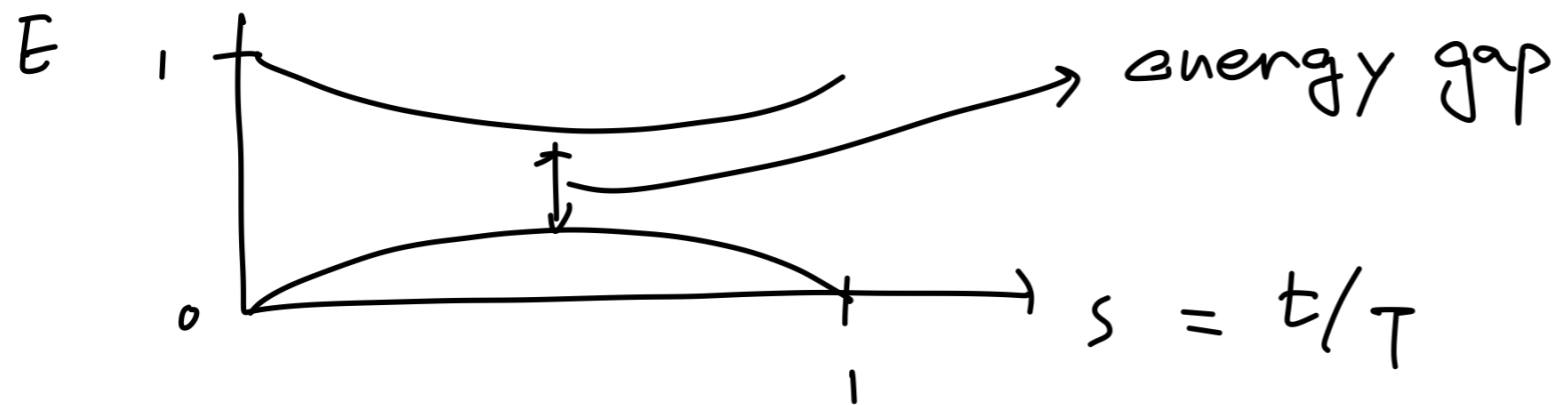
$$H(s) = (1-s)H_0 + sH_1 \quad s = s(t)$$

$$H_0 = \mathbb{I} - |\psi_0\rangle\langle\psi_0| \quad : \quad \text{ground state}$$

$$H_0 |\psi_0\rangle = 0 \cdot |\psi_0\rangle$$

$$H_1 = \mathbb{I} - |\psi_1\rangle\langle\psi_1| \quad : \quad \text{ground state}$$

$$H_1 |\psi_1\rangle = 0 \cdot |\psi_1\rangle$$



Adiabatic theorem

$$T \gg \frac{1}{\epsilon}$$

$$|\psi_0\rangle \rightarrow |\psi_1\rangle \quad \text{with prob. } (1-\epsilon^2)^2$$

$$|\psi_0\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$$

$$|\psi_1\rangle = \alpha |0\rangle + \beta |1\rangle$$

$$f \text{ is constant} \Leftrightarrow \begin{cases} \alpha = 1 \\ \beta = 0 \end{cases}$$

$$f \text{ is balanced} \Leftrightarrow \begin{cases} \alpha = 0 \\ \beta = 1 \end{cases}$$

$$\alpha = \frac{1}{2} \left((-1)^{f(0)} + (-1)^{f(1)} \right)$$

$$\beta = \frac{1}{2} \left((-1)^{f(0)} - (-1)^{f(1)} \right)$$

The Deutsch-Jozsa Problem

$$f : \{0,1\}^n \rightarrow \{0,1\}$$

f is constant if $f(x) = f(y) \quad \forall x, y \in \{0,1\}^n$

f is balanced if $|f^{-1}(0)| = |f^{-1}(1)|$

The Deutsch-Jozsa Problem

Given $f : \{0,1\}^n \rightarrow \{0,1\}$

determine if f is constant or balanced

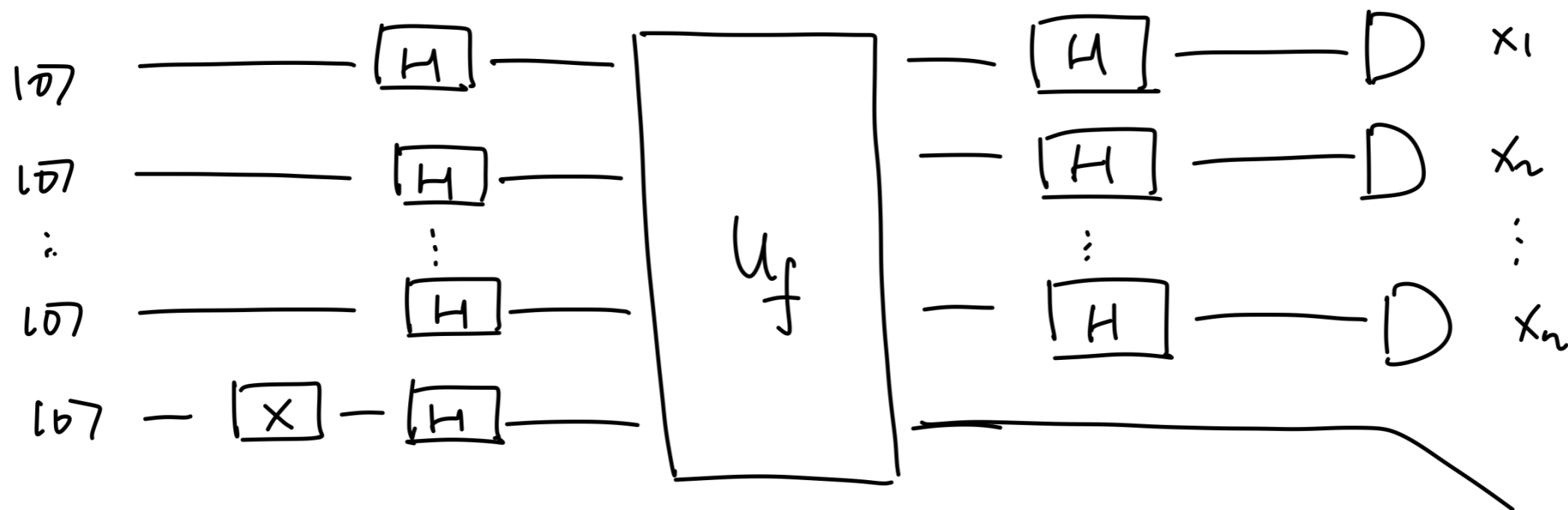
classical strategy $2^{n-1} + 1$

Quantum algorithm

$$U_f |x\rangle |y\rangle = |x\rangle |y + f(x)\rangle$$

$$\checkmark U_f |x^n\rangle |y\rangle = |x^n\rangle |y + f(x^n)\rangle$$

The Deutsch-Jozsa algorithm



f is constant $\iff x_1 x_2 \dots x_n = 00 \dots 0$

exercise. quantum state transformation from gates to gates

Remark. f is called only once.

The Deutsch-Jozsa Algorithm in adiabatic evolution

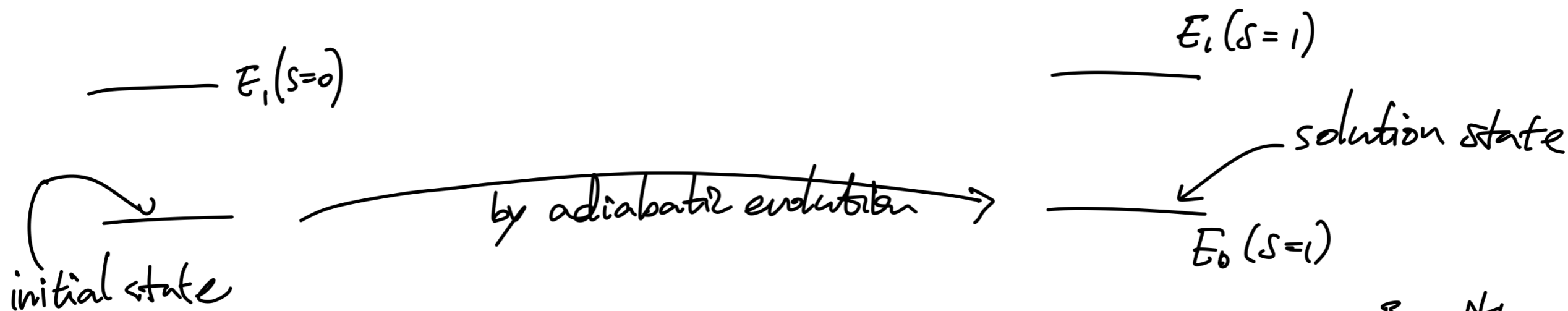
$$D \left[|s_0\rangle\langle s_0|, \text{tr}_A U_{SA} |0\rangle\langle 0|^{\otimes n} \otimes |A\rangle\langle A| U_{SA}^\dagger \right] < \epsilon$$

dynamics performs computation

$$H_0 = I - |t_0\rangle\langle t_0|$$

$$H_1 = I - |t_1\rangle\langle t_1|$$

$$H(s) = (1-s)H_0 + sH_1$$



$$|t_0\rangle = |t\rangle^{\otimes n}$$

$$f \text{ const.} \\ \Leftrightarrow |t_1\rangle = |0\rangle$$

Adiabatic theorem

$$T \gg \sqrt{N} / \epsilon$$

$$|t_1\rangle = \alpha |0\rangle + \frac{\beta}{\sqrt{N-1}} \sum_{k=1}^{N-1} |k\rangle$$

$$\alpha = \frac{1}{N} \left| \sum_{x \in \{0,1\}^n} (-1)^{f(x)} \right|$$

$$\beta = 1 - \alpha$$

$$H_0 = I - |\psi_0\rangle\langle\psi_0|$$

$$H_1 = I - |\psi_1\rangle\langle\psi_1|$$

$$H(s) = (1-s)H_0 + sH_1$$

$$E_1(s=0)$$

$$s(t) = t/T$$

$$E_1(s=1)$$

initial state

by adiabatic evolution

solution state

$$E_0(s=1)$$

$$|\psi_0\rangle = |t\rangle^{\otimes n}$$

$$|\psi_1\rangle = \frac{\alpha}{\sqrt{N/2}} \sum_{k=0}^{N/2-1} |2k\rangle + \frac{(-\alpha)^{N/2-1}}{\sqrt{N/2}} \sum_{i=0}^{N/2-1} |2i+1\rangle$$

$$\alpha = \frac{1}{N} \left| \sum_{x \in \{0,1\}^n} (-1)^{f(x)} \right|$$

Adiabatic theorem

$$T \gg \frac{4}{\epsilon} \sim O(N)$$

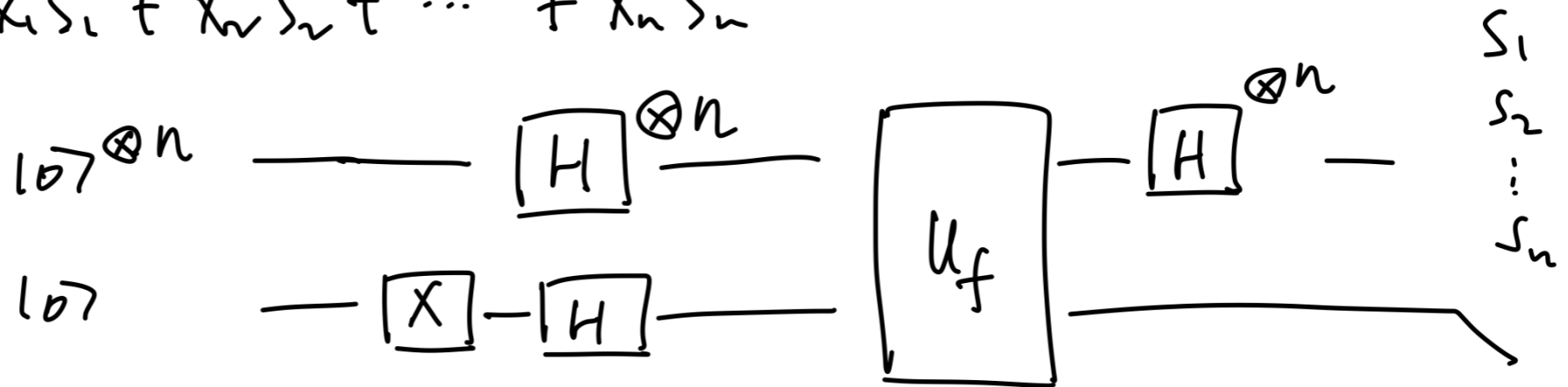
"no factor with n or N "

Bernstein-Vazirani algorithm

$$f_s(x) = x \cdot s : \{0,1\}^n \rightarrow \{0,1\}$$

$$x \cdot s = x_1 s_1 + x_2 s_2 + \dots + x_n s_n$$

Find s .



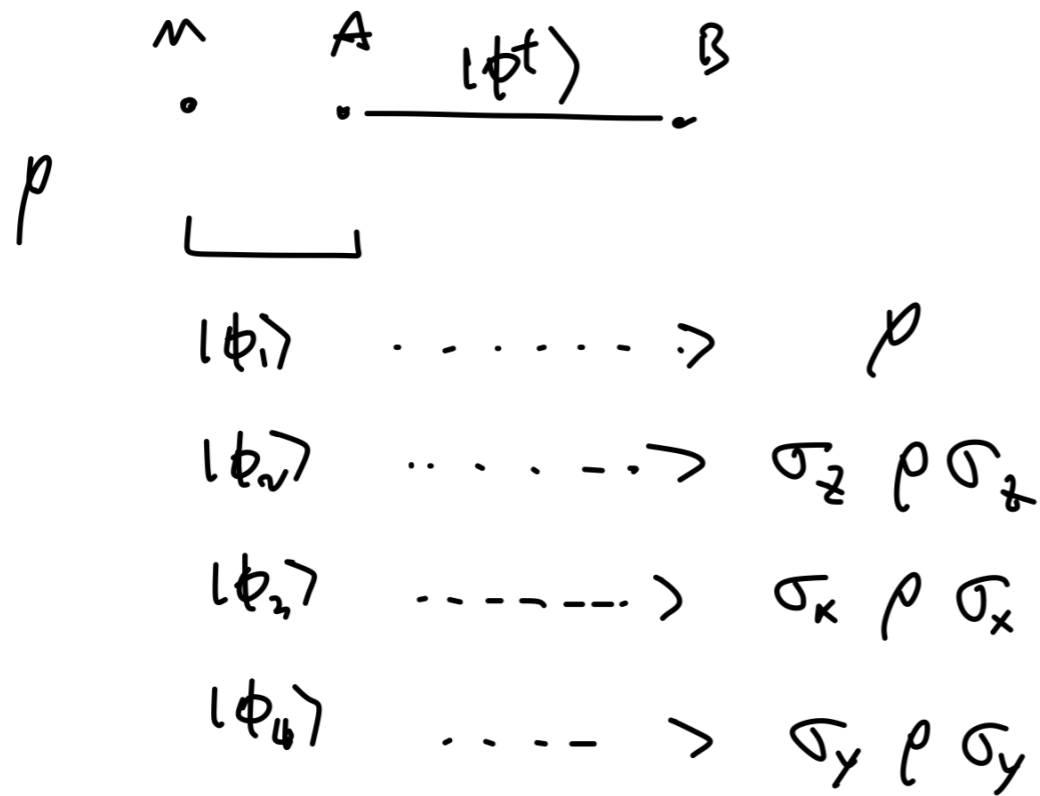
$$U_f |x\rangle |y\rangle = |x\rangle |y + f(x)\rangle$$

$$= |x\rangle |y + x \cdot s\rangle$$

Exercise. State transformation from a gate to a gate.

Measurement - Based Quantum Computation

Recall. Quantum teleportation



$$|\phi^t\rangle = \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle)$$

$$|\phi_1\rangle = \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle)$$

$$|\phi_2\rangle = \frac{1}{\sqrt{2}} (|00\rangle - |11\rangle)$$

$$|\phi_3\rangle = \frac{1}{\sqrt{2}} (|01\rangle + |10\rangle)$$

$$|\phi_4\rangle = \frac{1}{\sqrt{2}} (|01\rangle - |10\rangle)$$

$$\Rightarrow \Lambda_i[\rho] = 4 \operatorname{tr}_{MA} \left(\rho \otimes \sum_{AB} |\phi^t\rangle \langle \phi^t| \right) |\phi_i\rangle \langle \phi_i|_{MA}$$

↑
single-qubit
dynamics

measurement on entangled states

Recall. CNOT + single-qubit operations \sim universal quantum computation

exercise 


 \sim quantum teleportation.

\Rightarrow Universal quantum computation can be realized
by entangled states and measurements.

Quantum Algorithms : Solving mathematical problems
with quantum systems

- Basics of Quantum Information Processing
- Idea of quantum computation
- Some Algorithms & Models
 - DJ algorithm i) circuit models ii) Adiabatic.